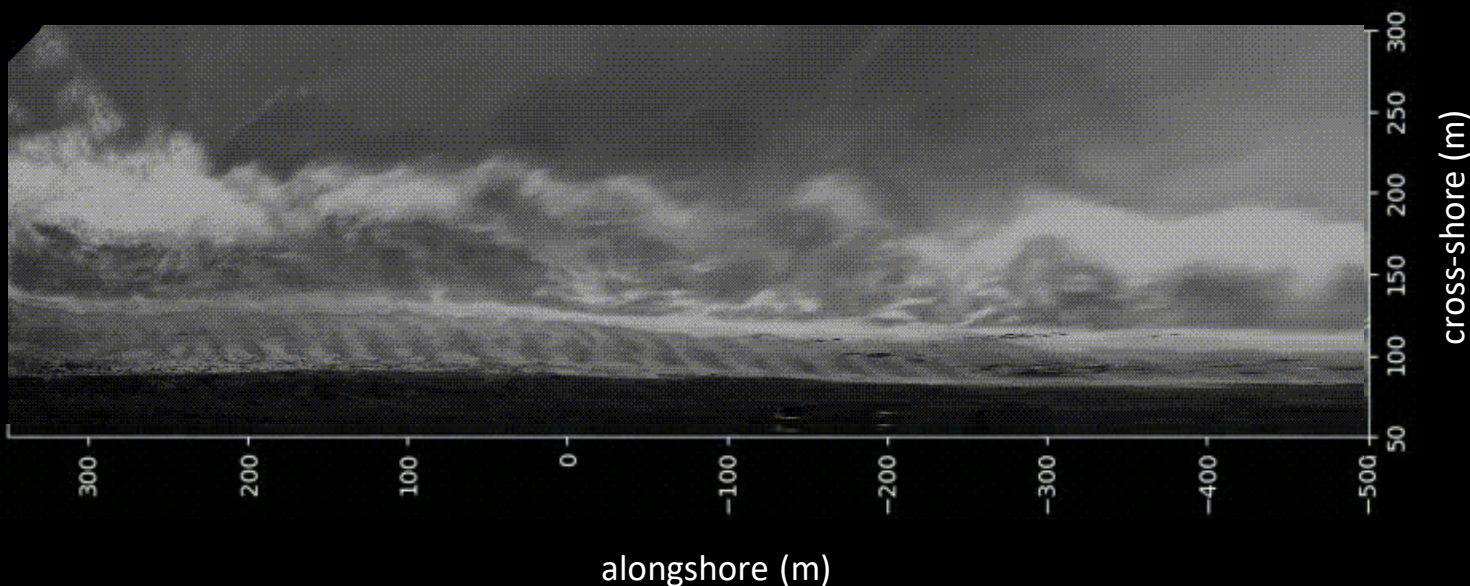


Remotely sensed nearshore currents: wave-averaged movies & surf zone drifter deployments

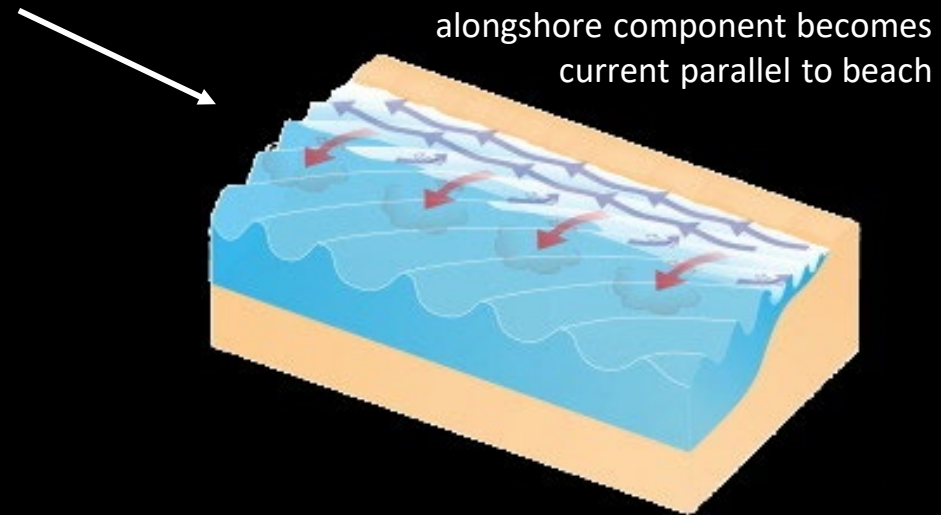
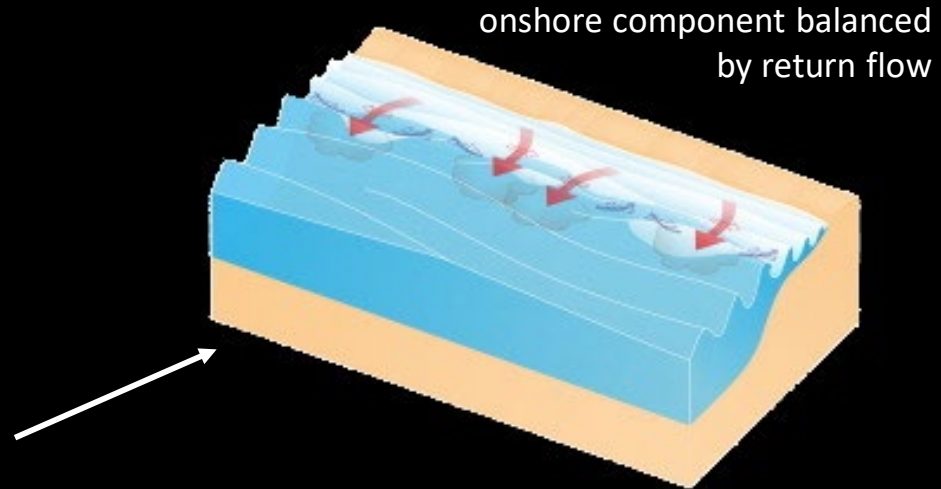
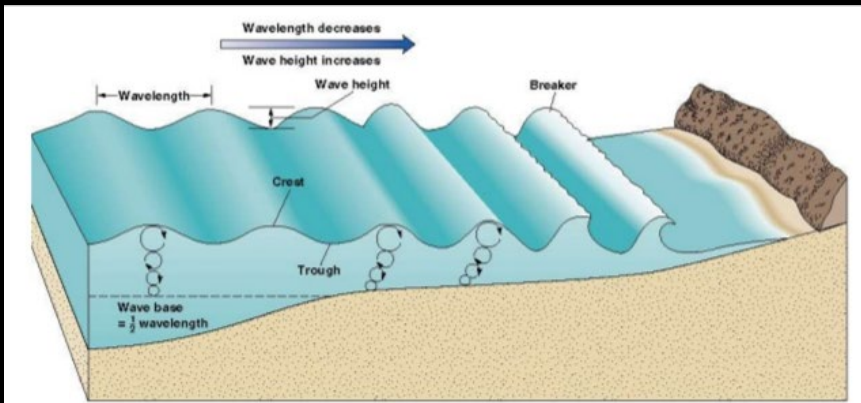
Dylan Anderson^{1,2}, Spicer Bak¹, Rob Holman³, Greg Wilson³

US Army Corps of Engineers – Engineer Research & Development Center¹
Oregon State University – College of Earth, Ocean, & Atmospheric Sciences³



Nearshore circulation is mainly forced by excess momentum resulting from wave breaking

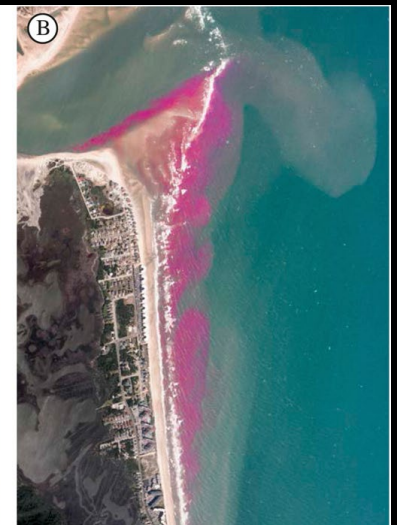
Wave energy is “released” at the break point



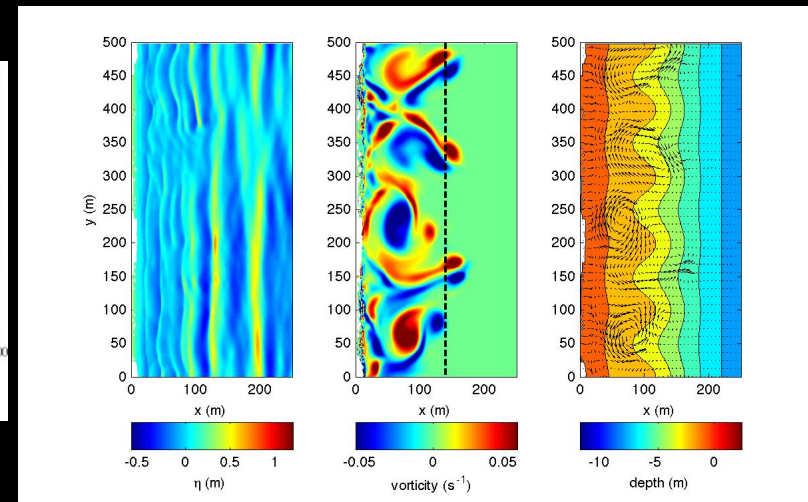
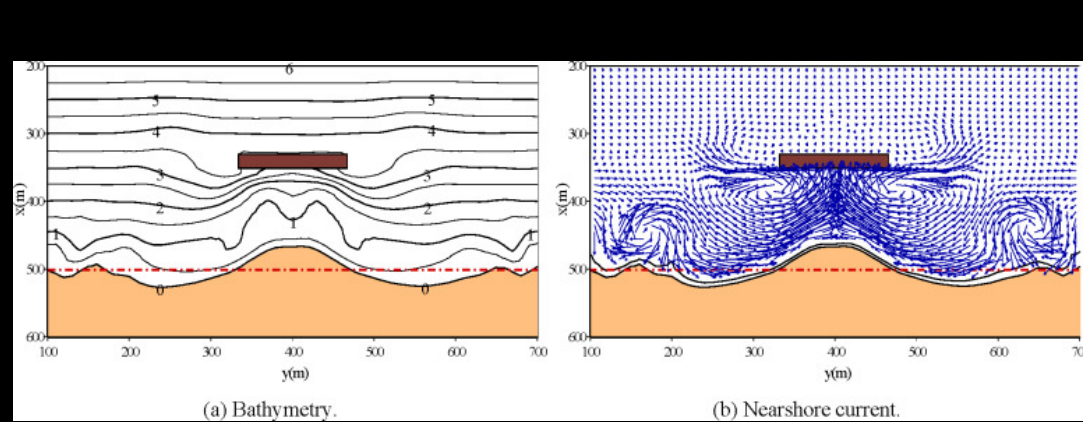
Resulting currents are relevant to a broad range of disciplines



- Swimmer safety
- Coastal structure interaction
- Transport and mixing of sediment, nutrients and pollutants



Considerable model development in the coastal community



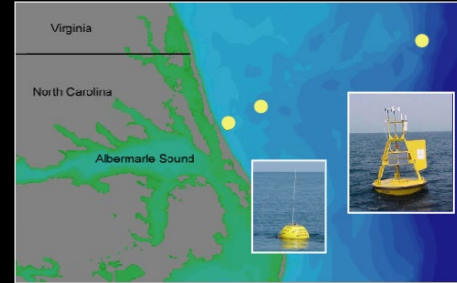
But considerable problems obtaining validation data...



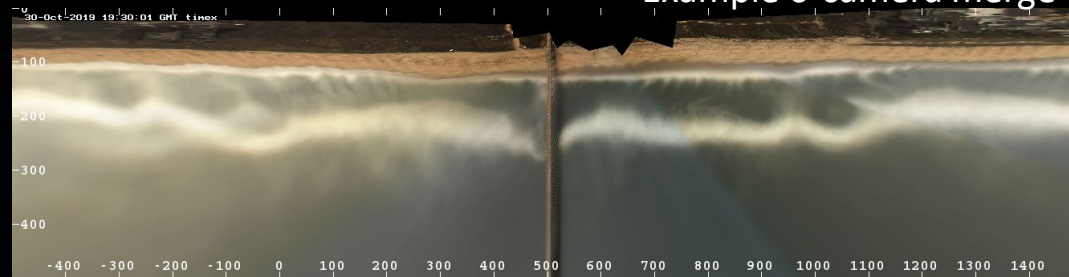
USACE Field Research Facility

- How can we quantify/asses model predictive capability to spatially/temporally variable circulation patterns?
- Goal: develop remotely-sensed product built on existing coastal imagery technology.

North Carolina, USA



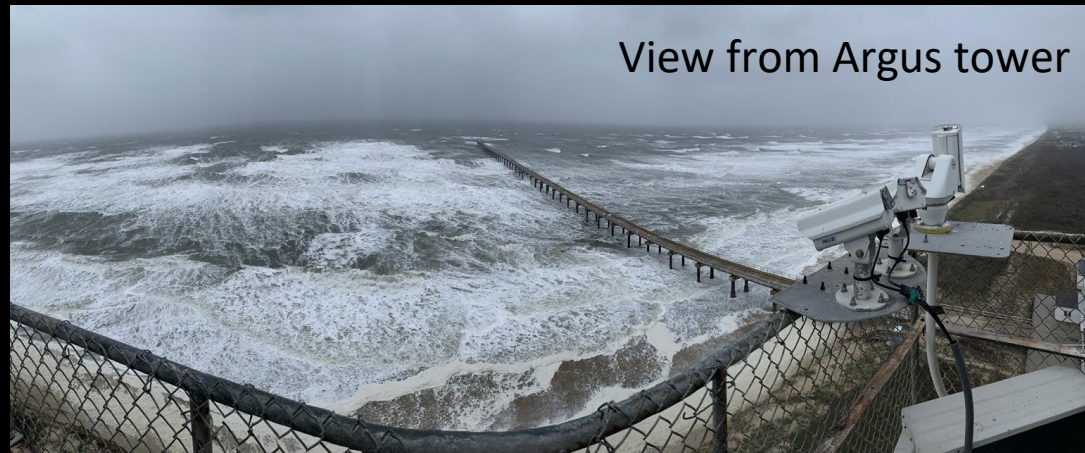
Example 6-camera merge



Argus tower

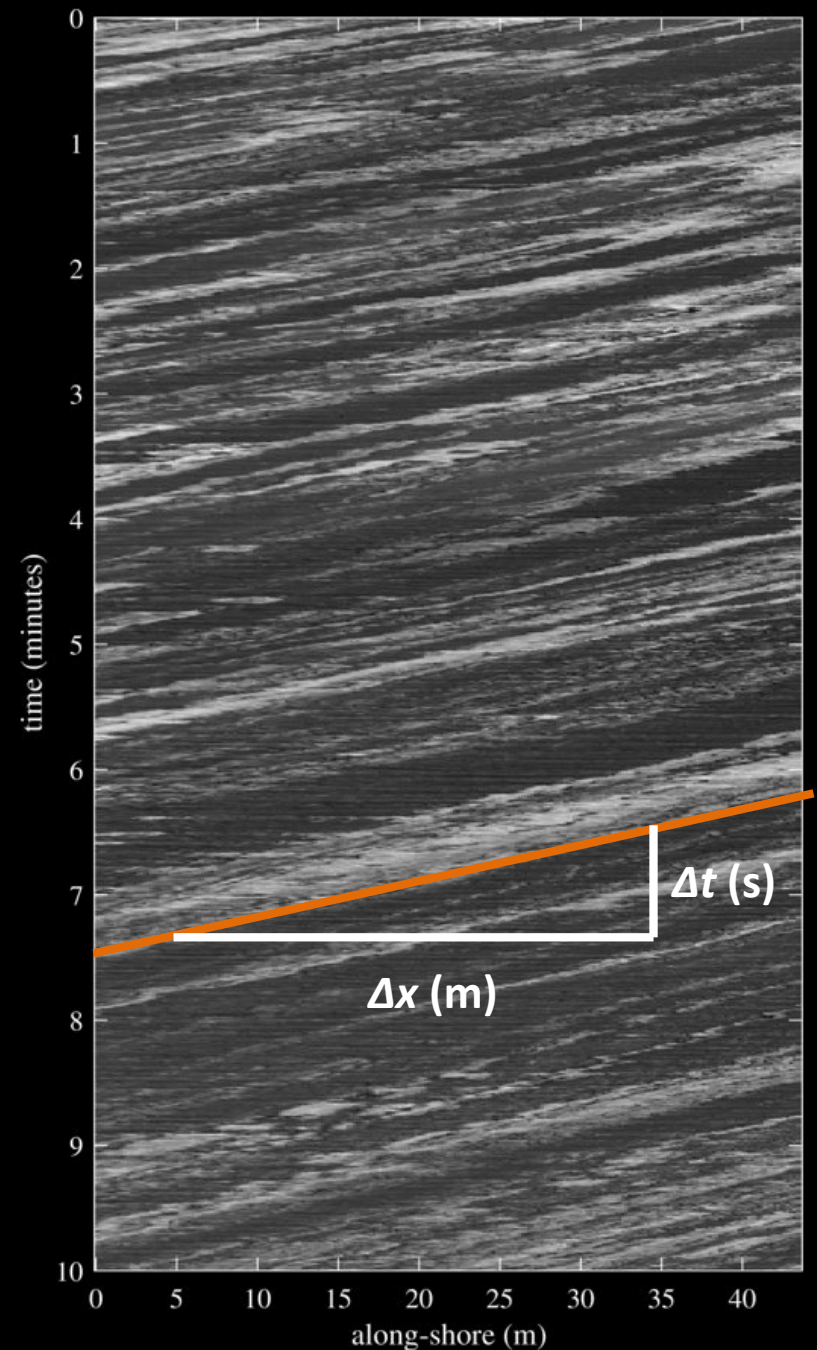


View from Argus tower



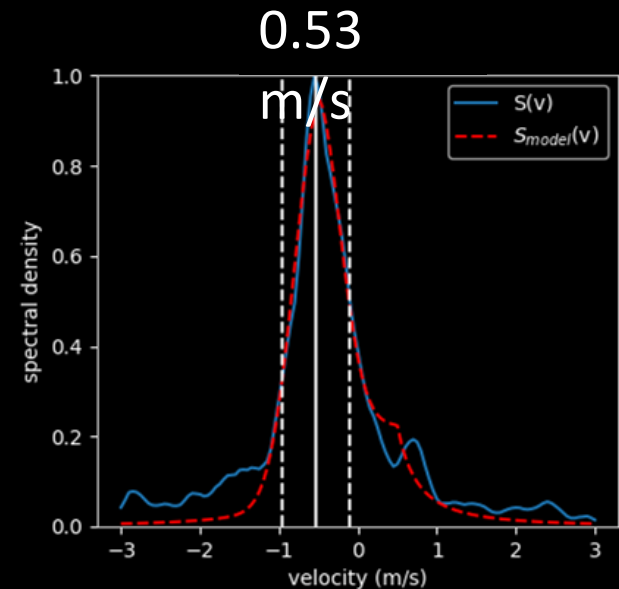
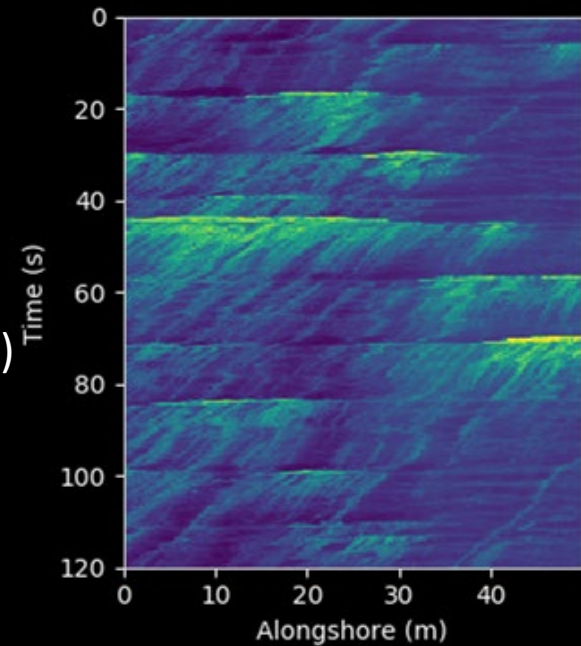
Optical currents can be obtained by tracking foam

Alongshore timestack:
extract line of pixels from every
frame in the 17 minute recording



Optical currents can be obtained by tracking foam

Fourier Transformation – “vBar” (Chickadel et al. 2003)
Radon Transformation (Almar et al. 2016)





Oysterville, WA: SEDEX2
(Sandbar Aeolian Dune
Exchange Experiment)

10 second loop from a UAV's 30 minute movie of the surfzone (2 Hz images)

Dominant signal is incident wave energy

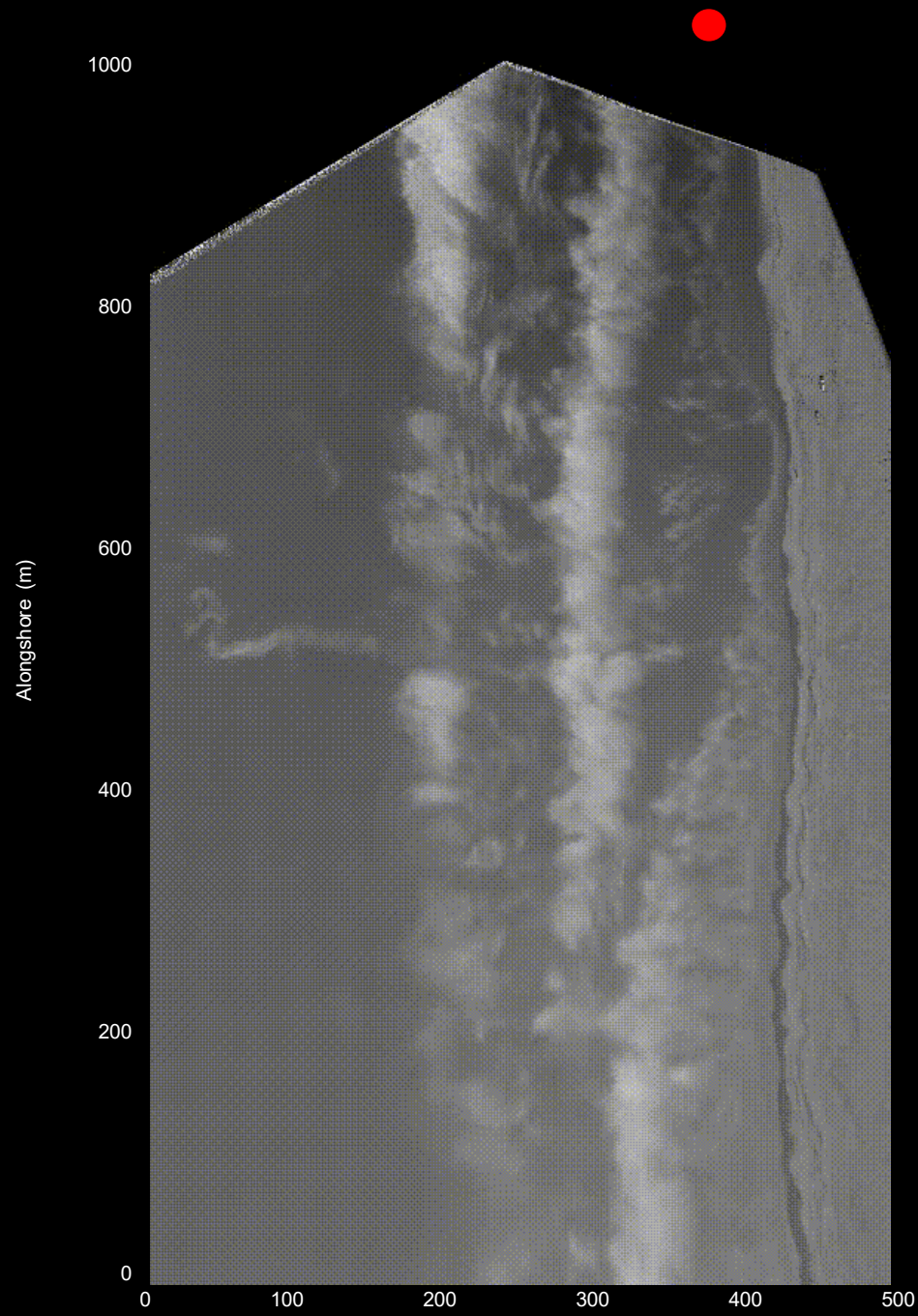


Oysterville, WA: SEDEX2
(Sandbar Aeolian Dune
Exchange Experiment)

Temporal average of images (20 second averages with 10 second time step)

Reduce this signal by considering it “noise”

Stabilized and Rectified with CIRN Toolbox

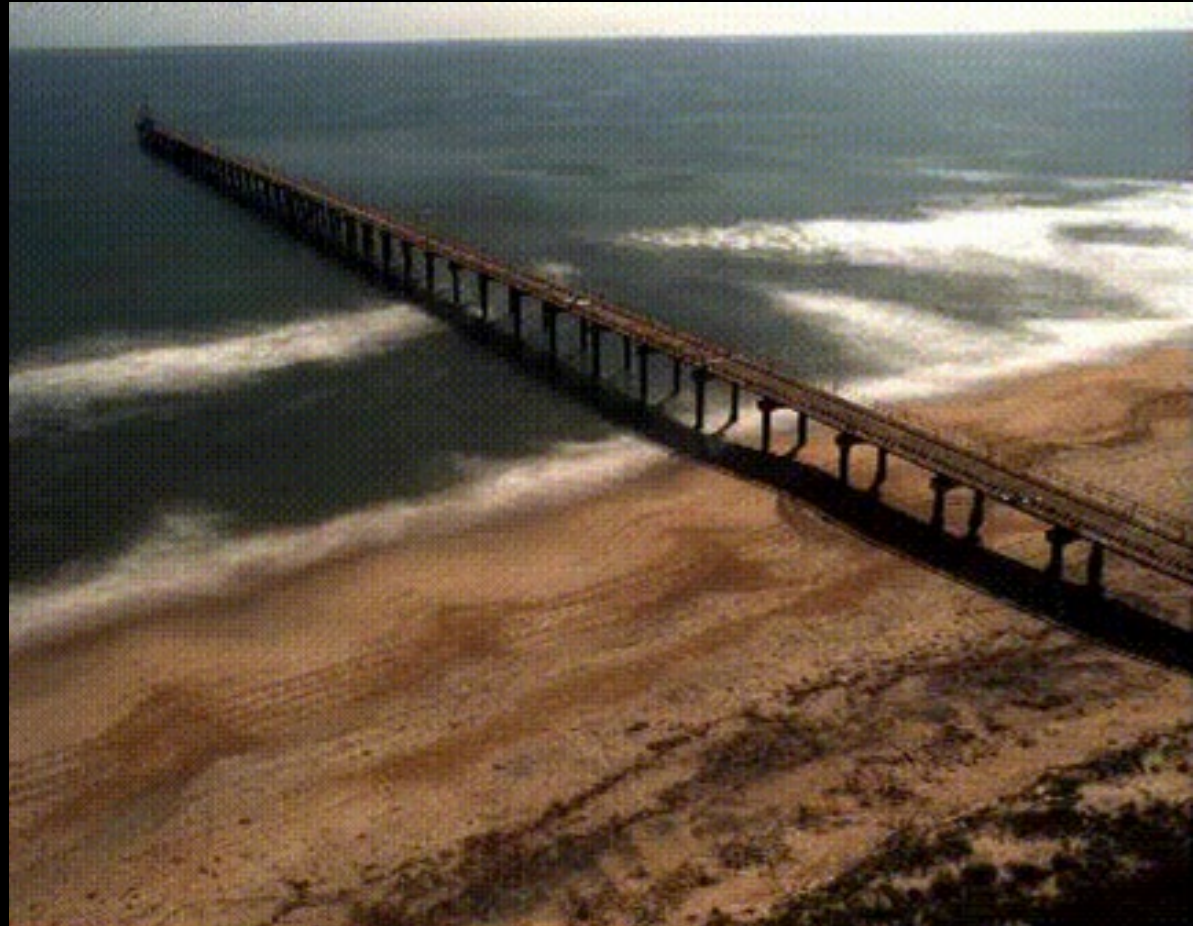


Wave-Averaged Movie (WAM)

- 20s averages, with a 10s step (50% overlap)
- 1m x 1m rectified grid
- New Argus product saved every 2 hours at FRF

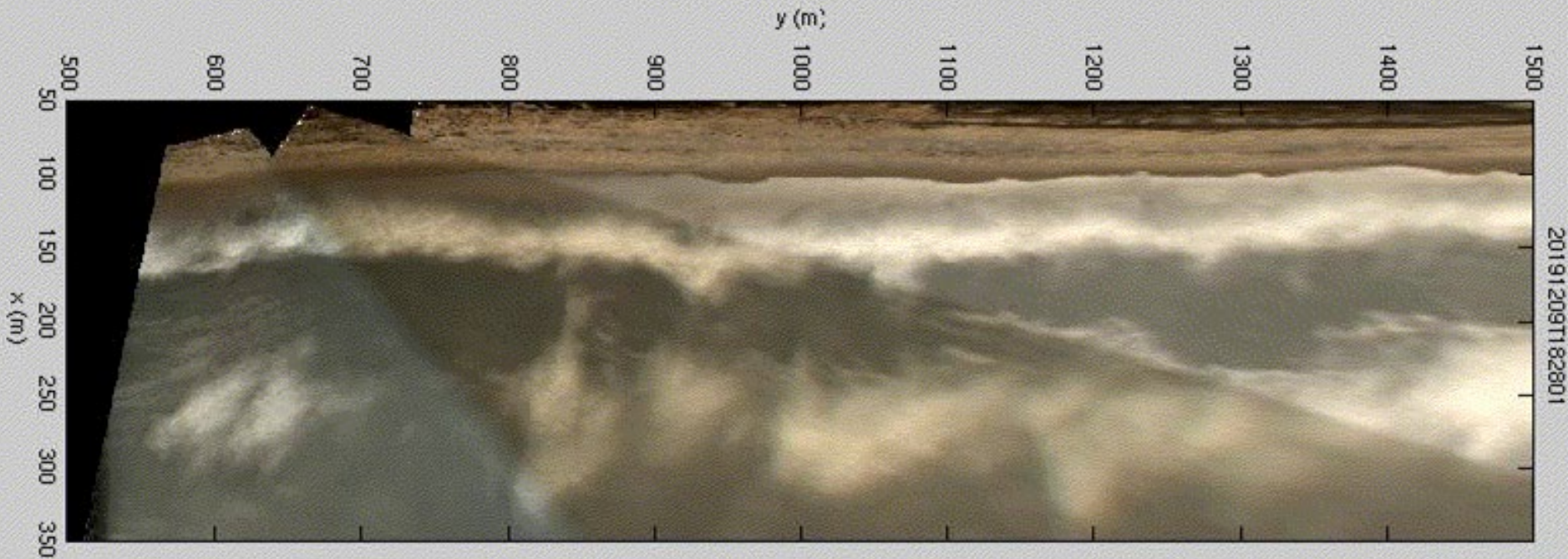


- Argus tower: 43 m tall, 6 cameras observing a longshore distance of several kilometers
- 2 Hz for 17 minutes



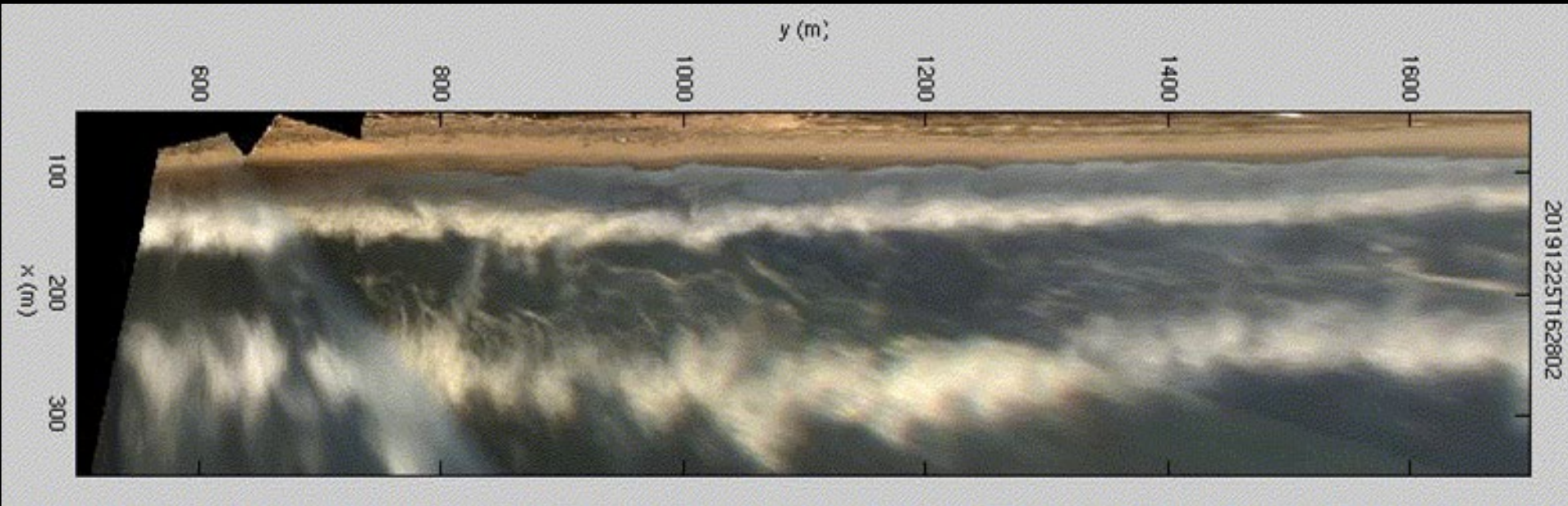
Wave-Averaged Movie (WAM)

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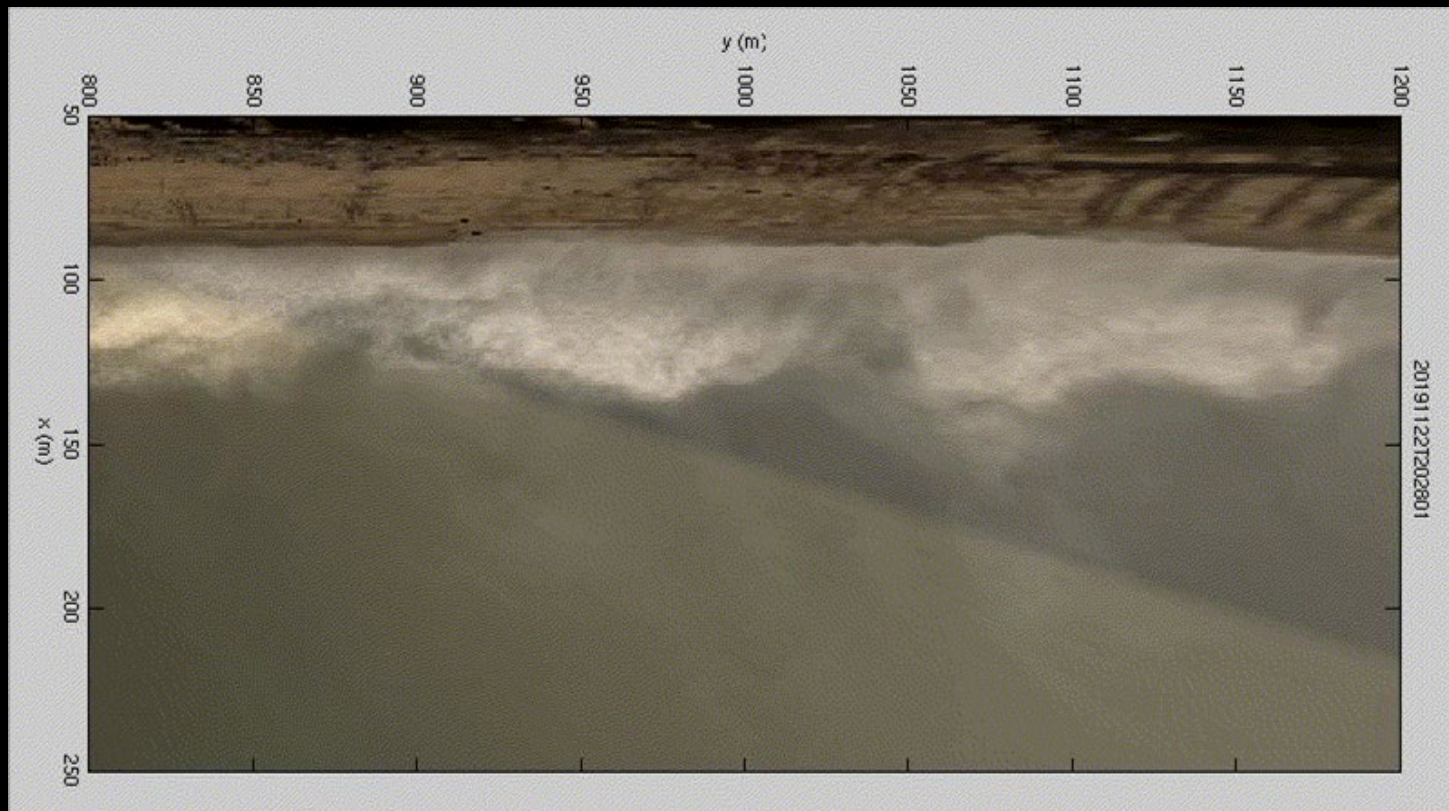
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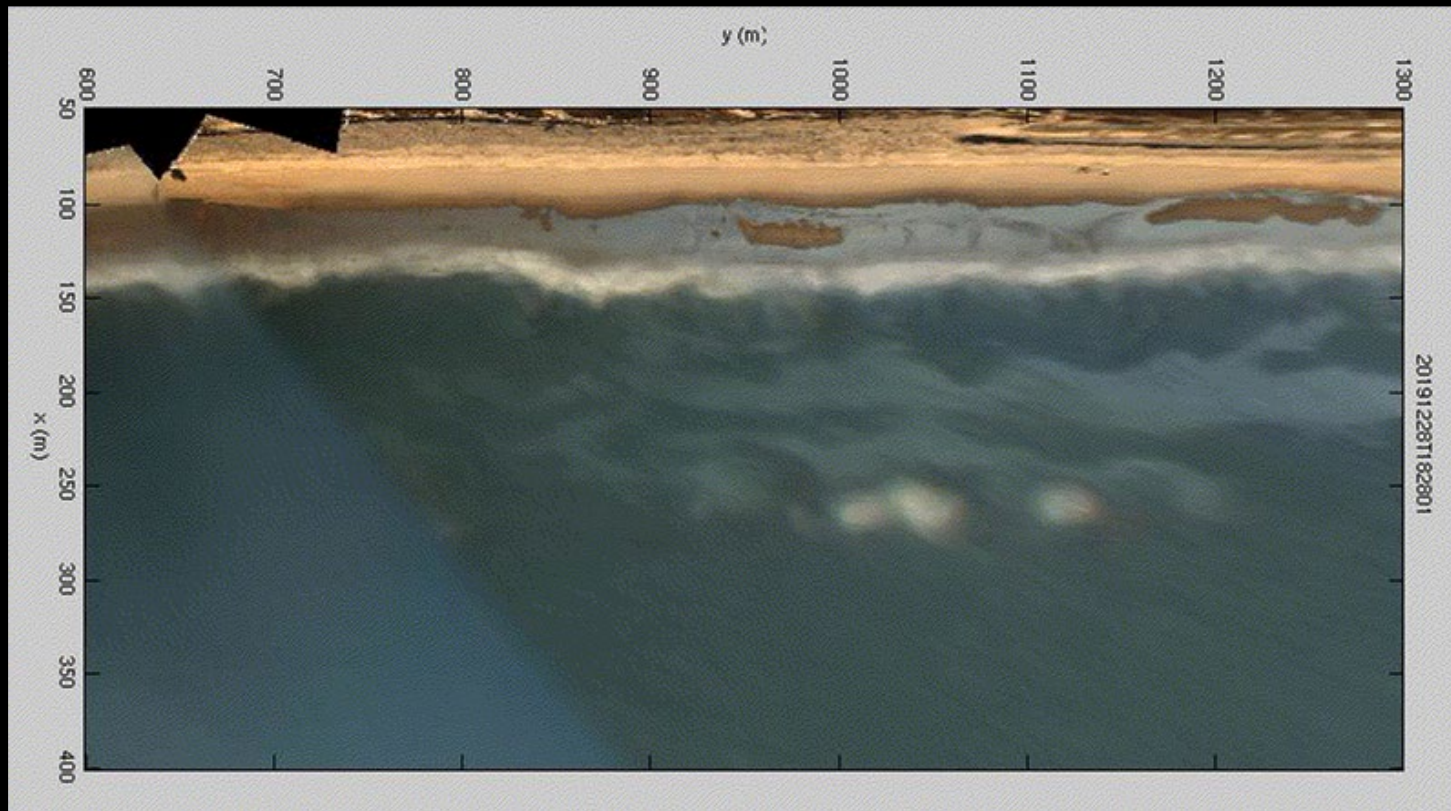
Wave-Averaged Movie (WAM)

- 20s averages, with a 10s step (50% overlap)
- 1m x 1m rectified grid
- New Argus product saved every 2 hours at FRF



Wave-Averaged Movie (WAM)

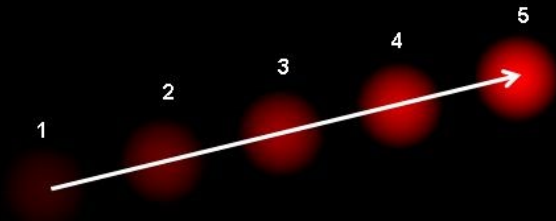
- 20s averages, with a 10s step (50% overlap)
- 1m x 1m rectified grid
- New Argus product saved every 2 hours at FRF



Wave-Averaged Movie (WAM)

- 20s averages, with a 10s step (50% overlap)
- 1m x 1m rectified grid
- New Argus product saved every 2 hours at FRF

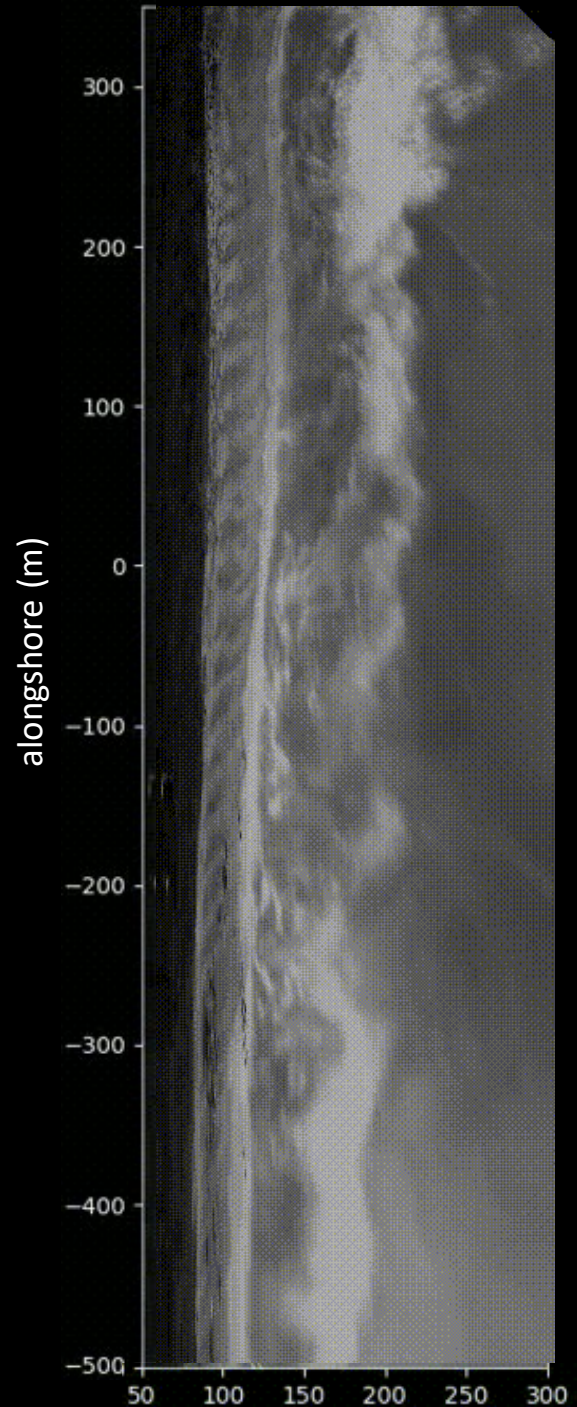
Optical Flow



Solves for gradients of image intensity in both space and time (Farneback 2003)

$$\frac{\partial I}{\partial x}u + \frac{\partial I}{\partial y}v + \frac{\partial I}{\partial t} = 0$$

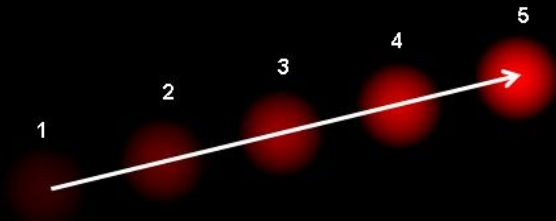
Gives a direction and magnitude at every pixel between every frame in the video



Wave-Averaged Movie (WAM)

- 20s averages, with a 10s step (50% overlap)
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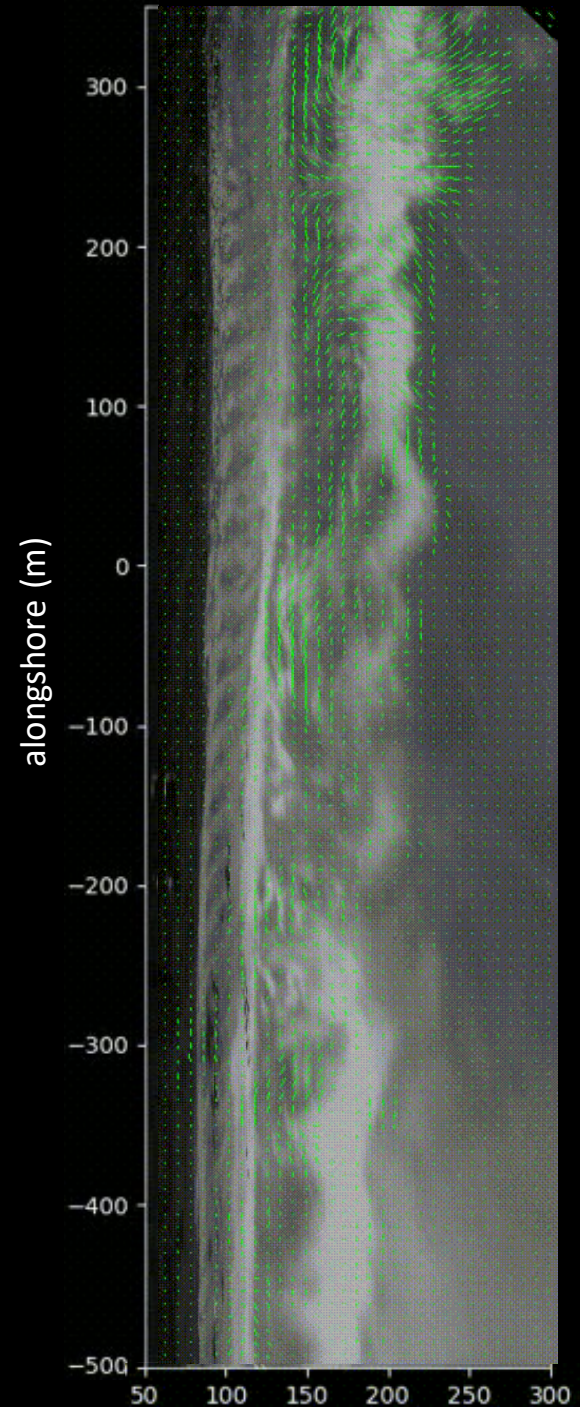
Optical Flow



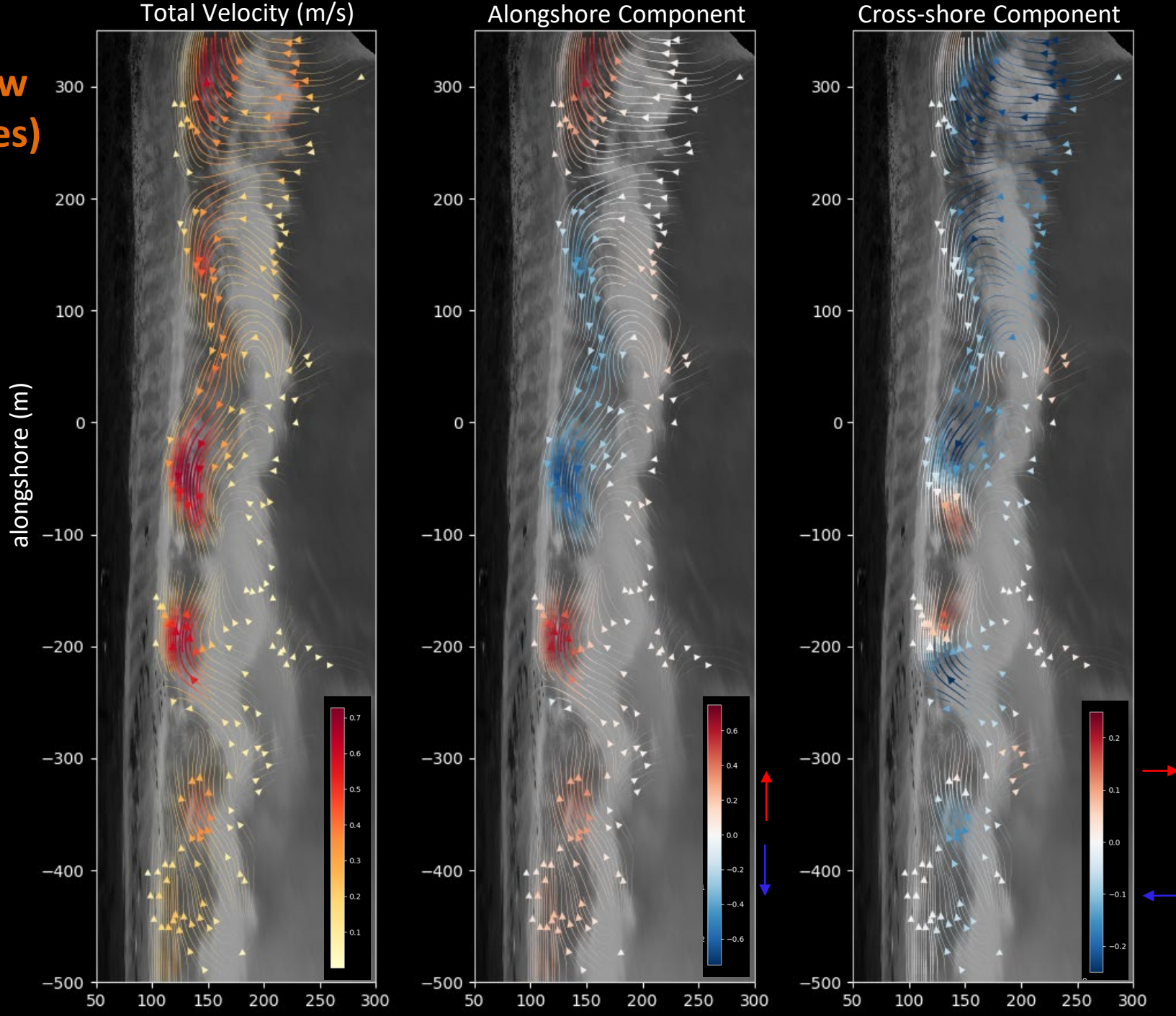
Solves for gradients of image intensity in both space and time (Farneback 2003)

$$\frac{\partial I}{\partial x}u + \frac{\partial I}{\partial y}v + \frac{\partial I}{\partial t} = 0$$

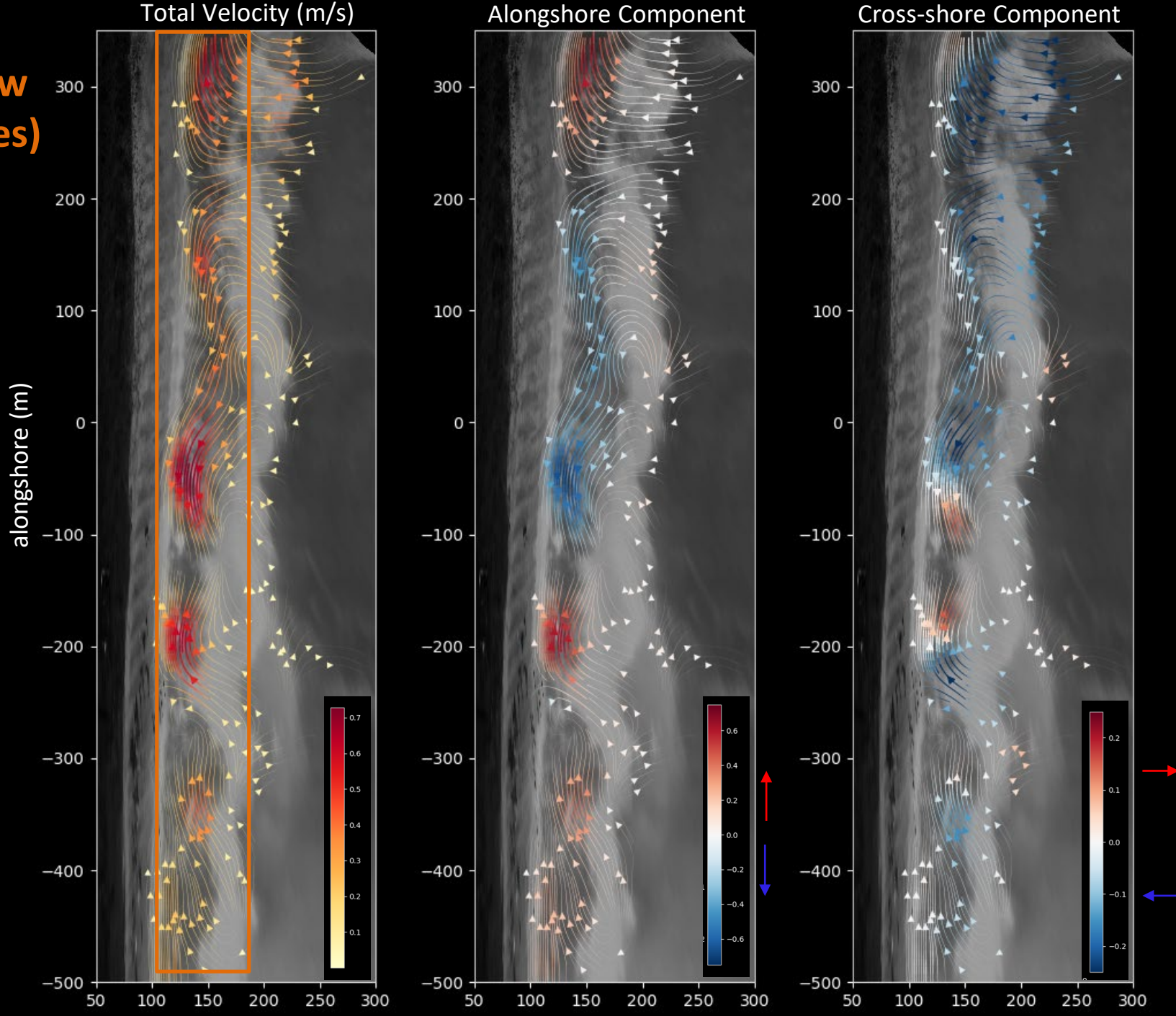
Gives a direction and magnitude at every pixel between every frame in the video



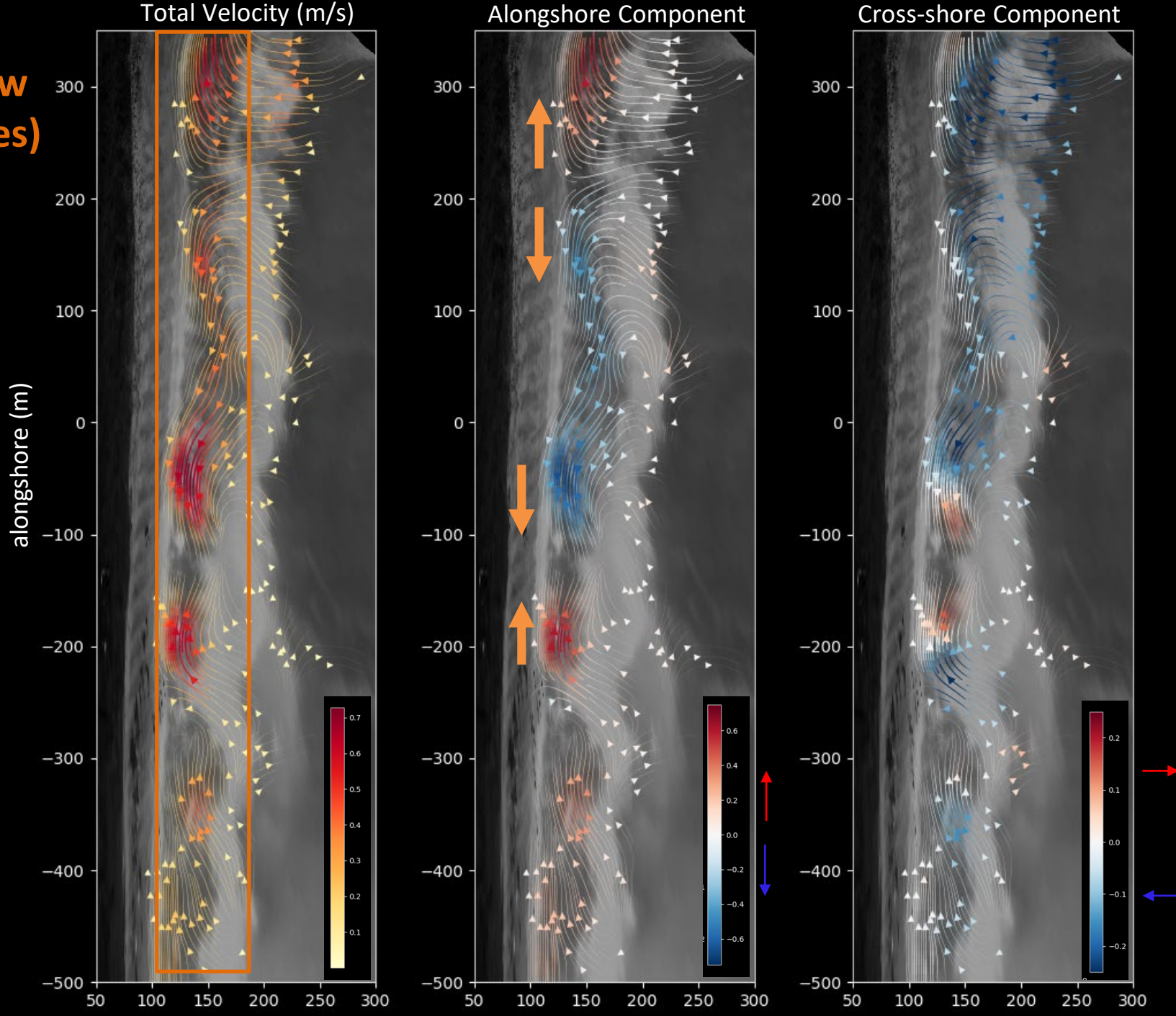
**Mean Flow
(180 frames)**



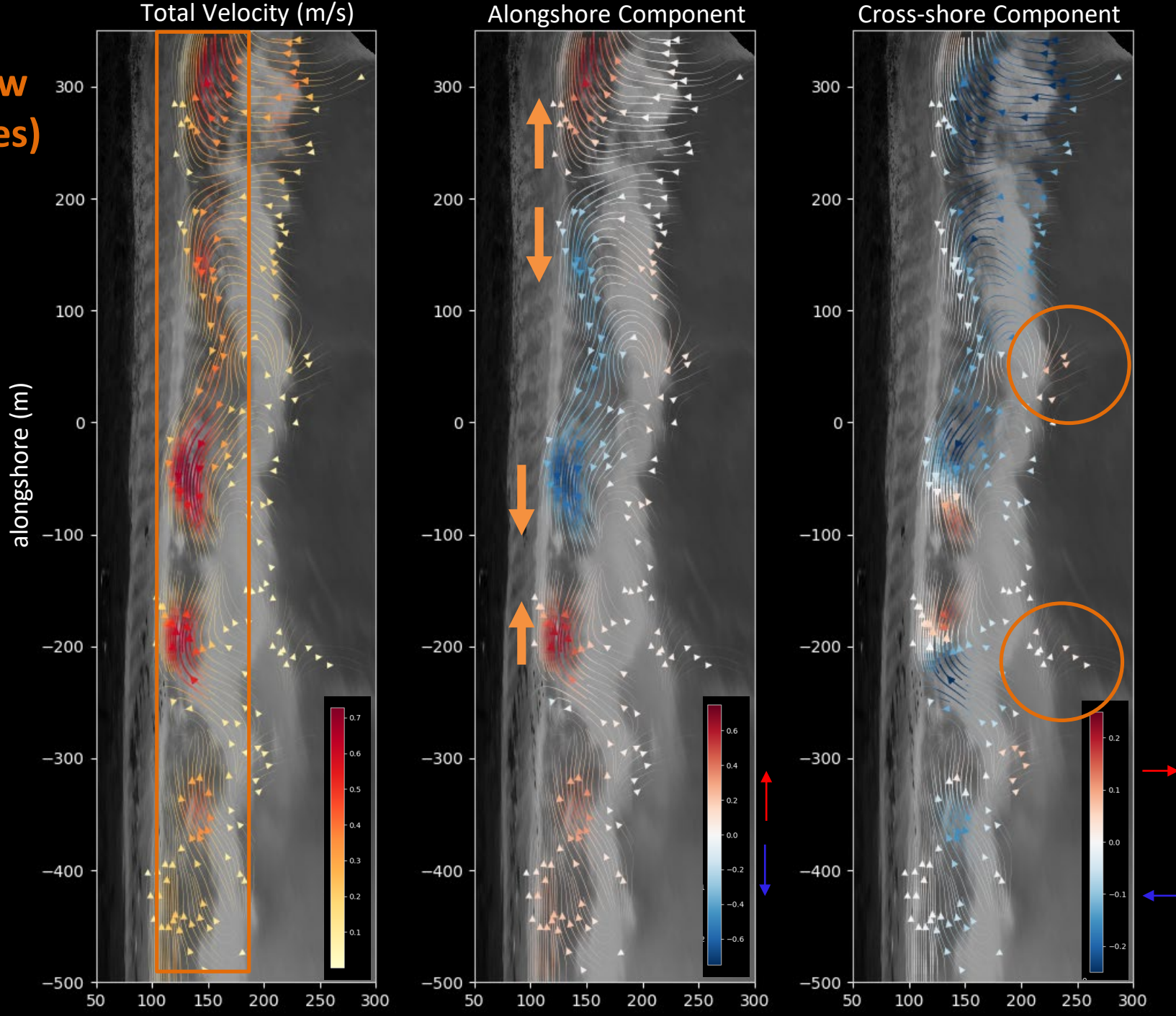
**Mean Flow
(180 frames)**



**Mean Flow
(180 frames)**

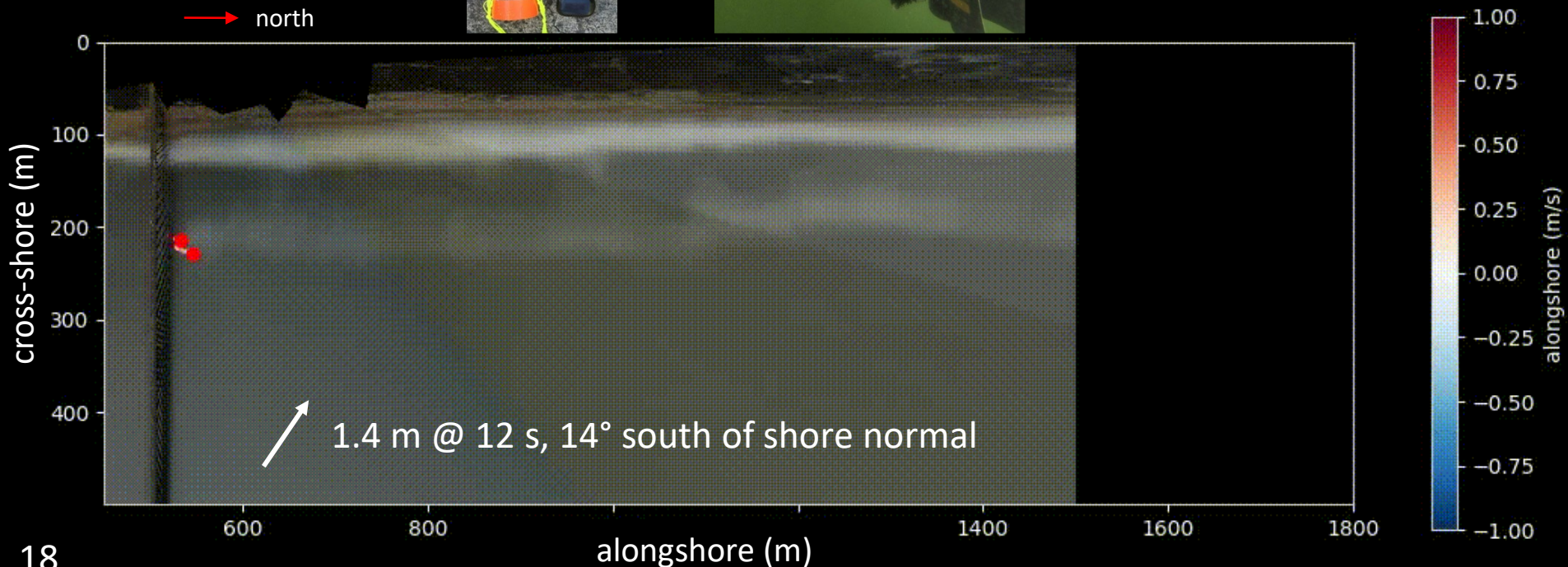
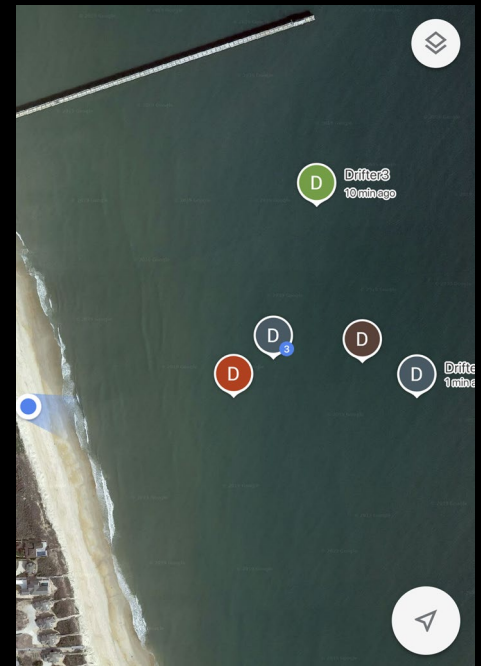


**Mean Flow
(180 frames)**



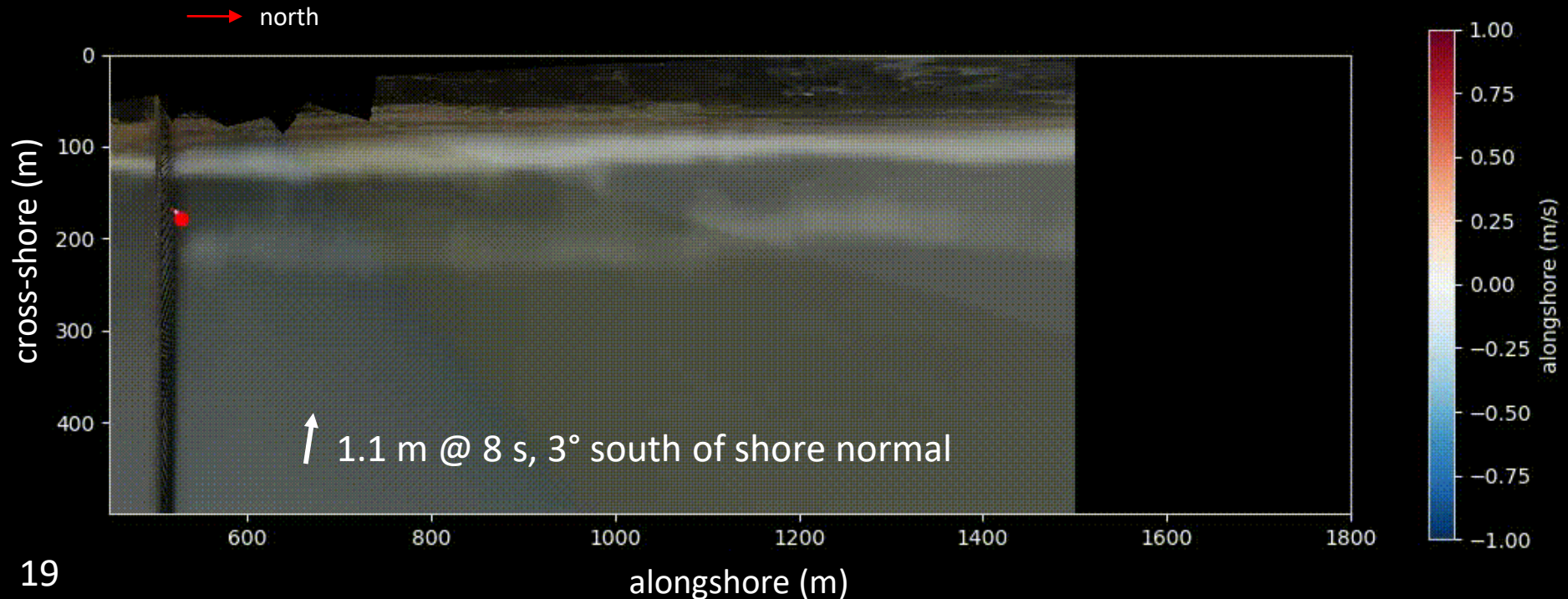
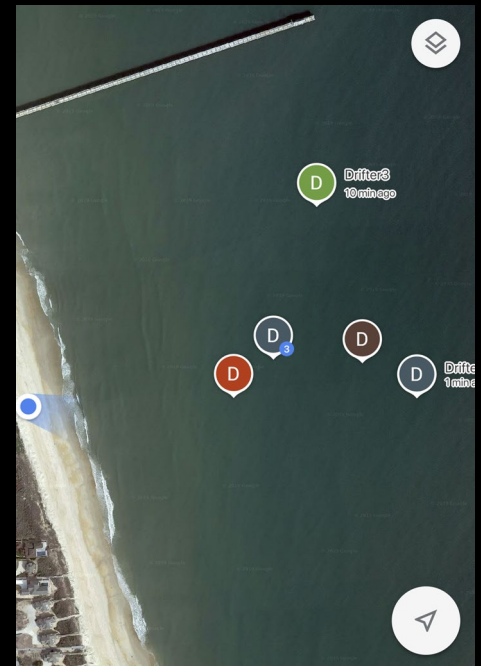
Drifter deployments at the FRF

- Dropped drifters off the pier at varying cross-shore distances during DUNEX pilot
- Tracked in live time with mobile devices
- Spit out by the shore-break (typically)



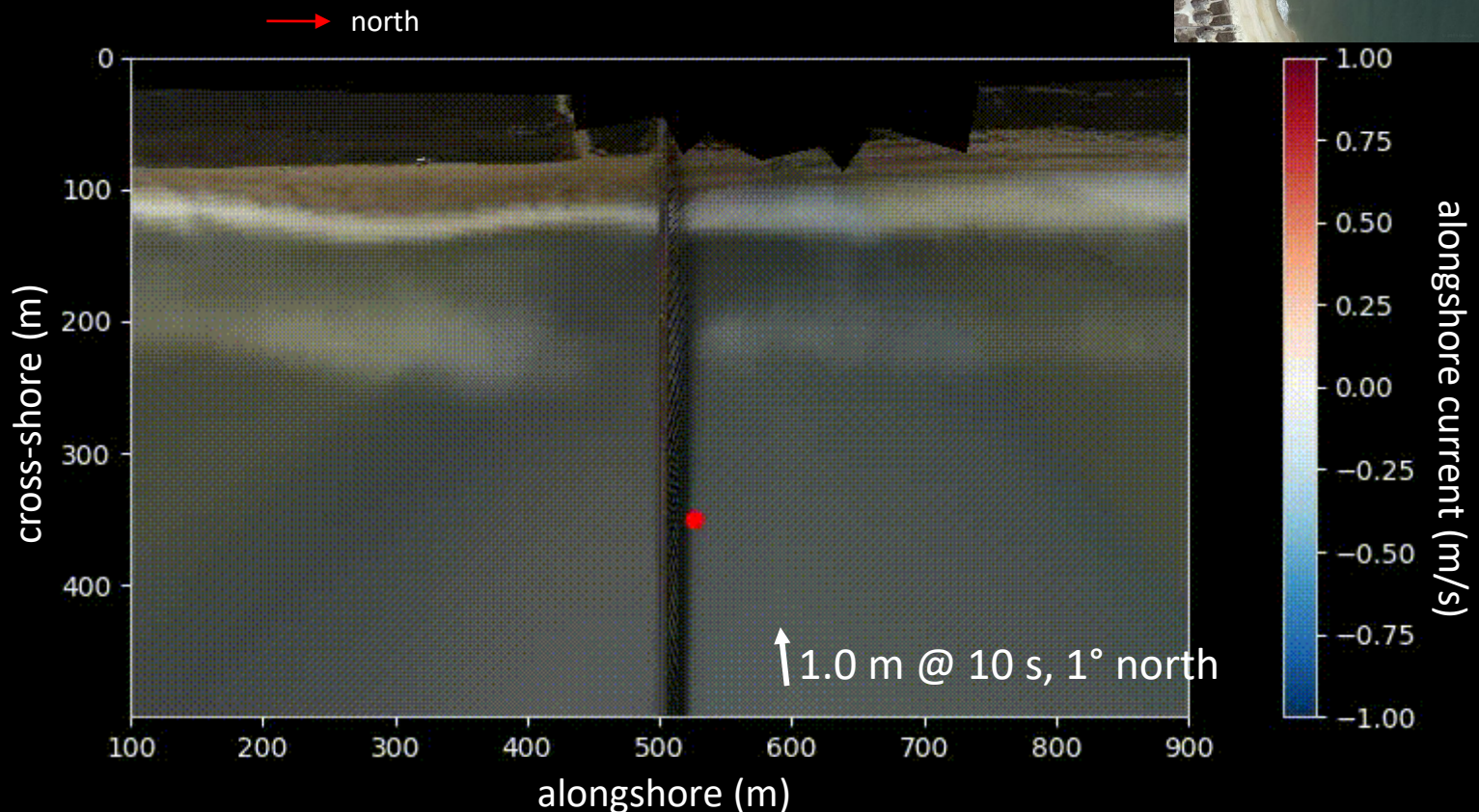
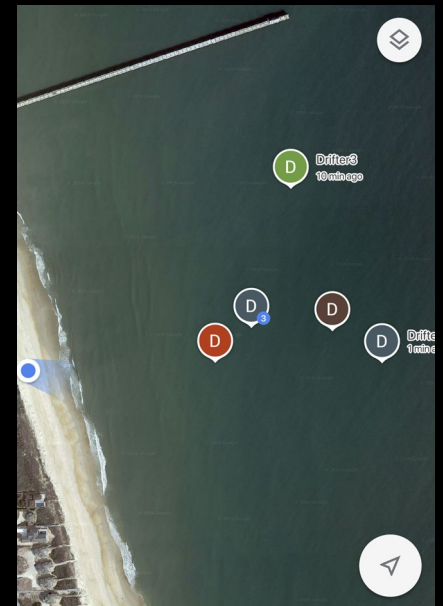
Drifter deployments at the FRF

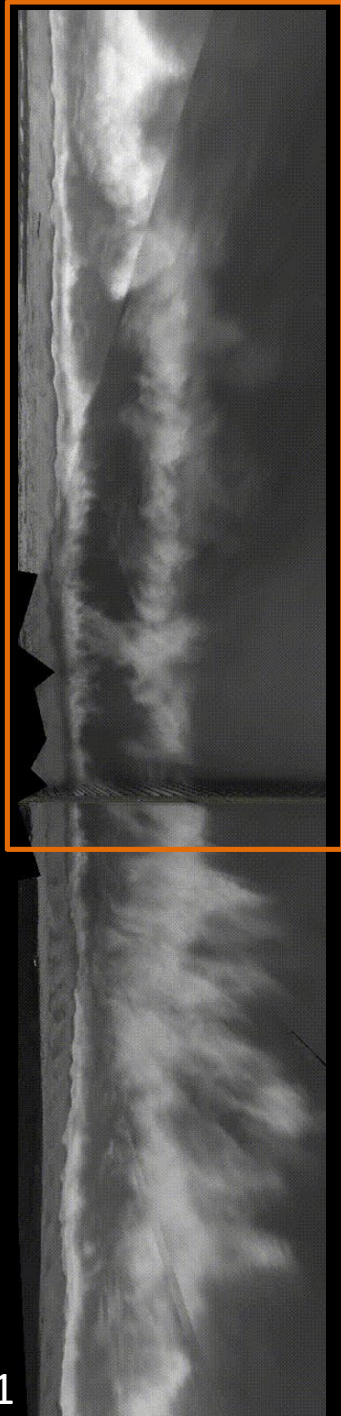
- Dropped drifters off the pier at varying cross-shore distances during DUNEX pilot
- Tracked in live time with mobile devices
- Spit out by the shore-break (typically)



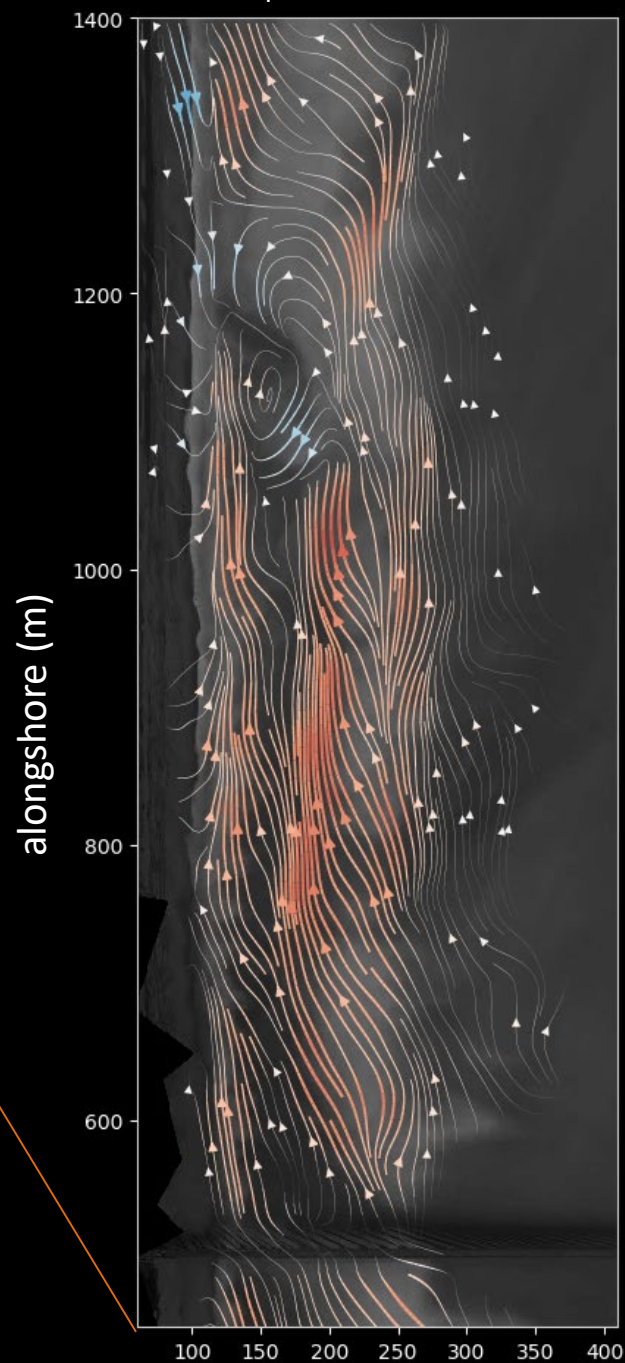
Drifter deployments at the FRF

- Dropped drifters off the pier at varying cross-shore distances during DUNEX Pilot
- Tracked in live time with mobile devices
- Allowed to freely float alongshore & onshore
- Spit out by the shore-break (typically)

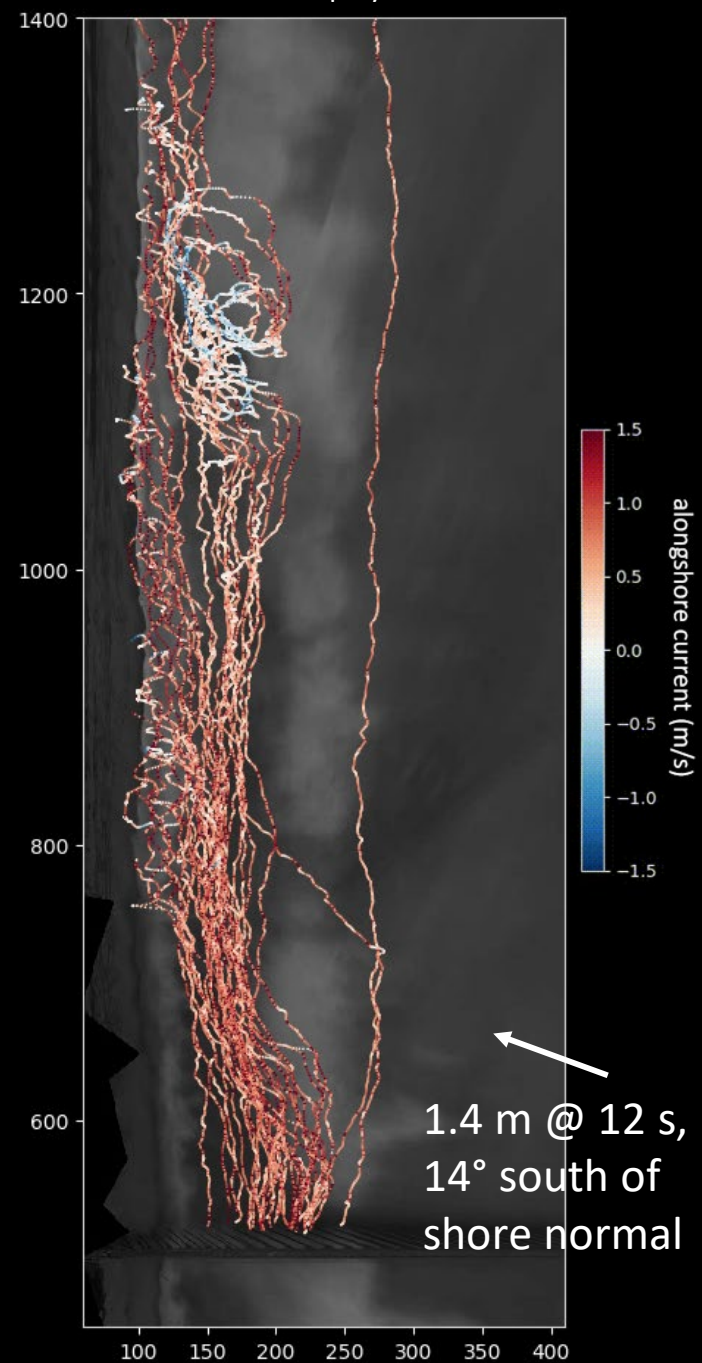




Optical Flow of WAM

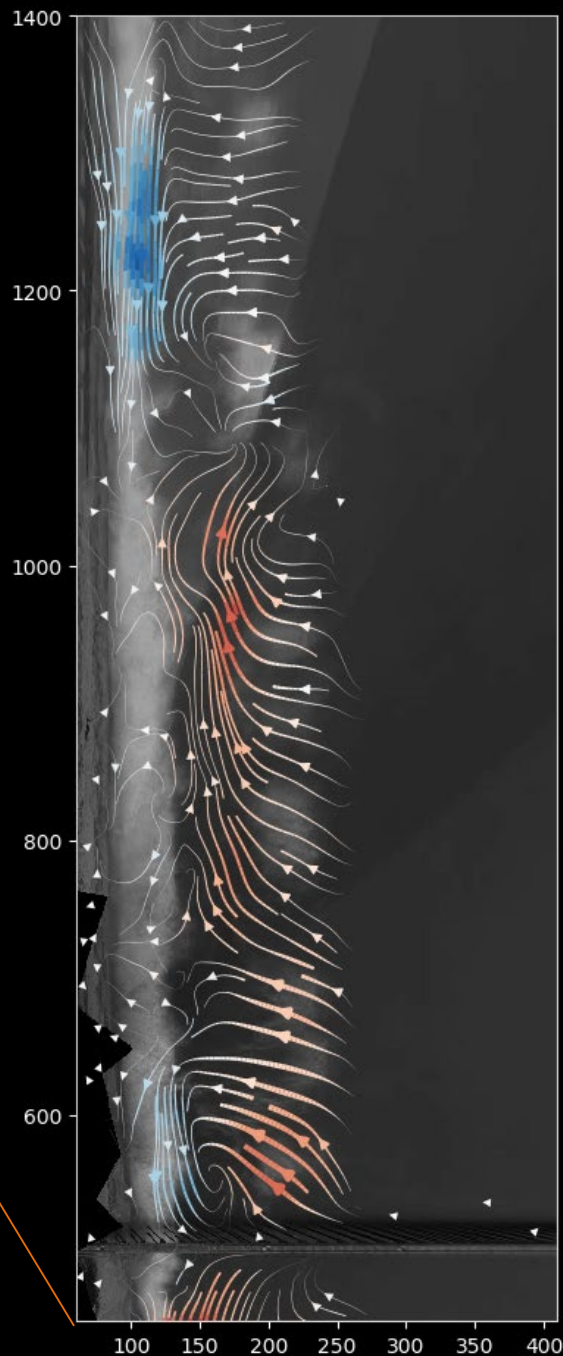


Drifter Deployment

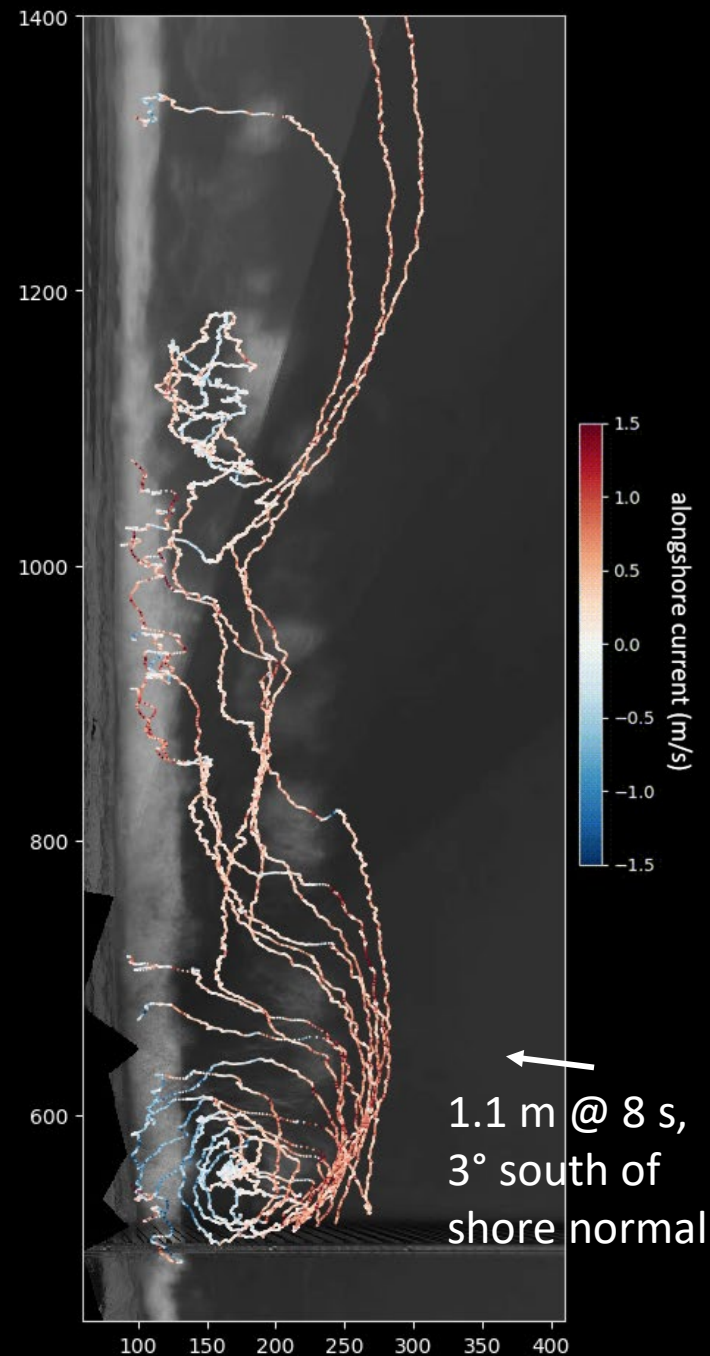


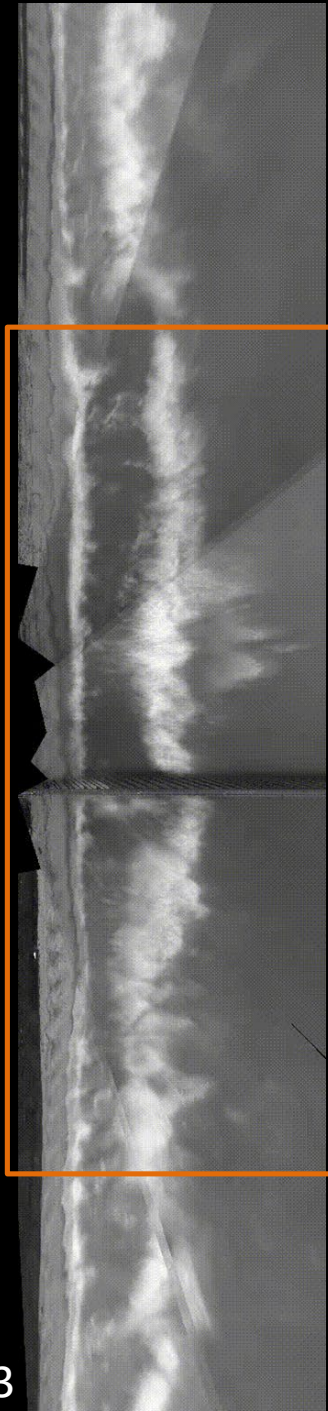


Optical Flow of WAM

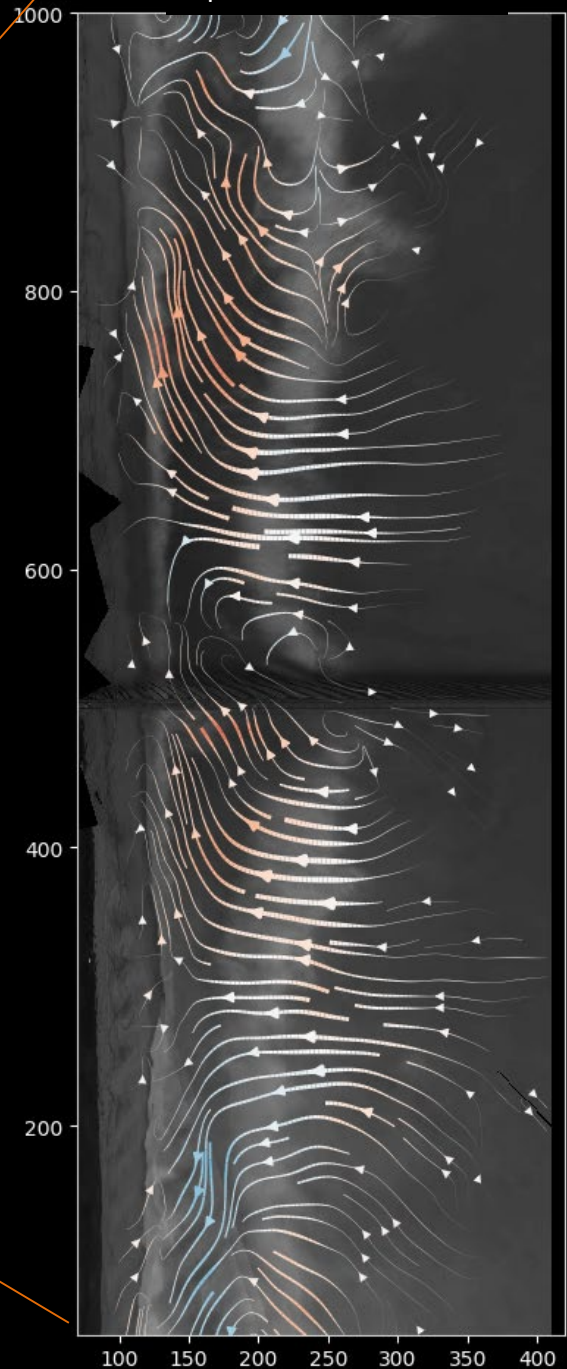


Drifter Deployment

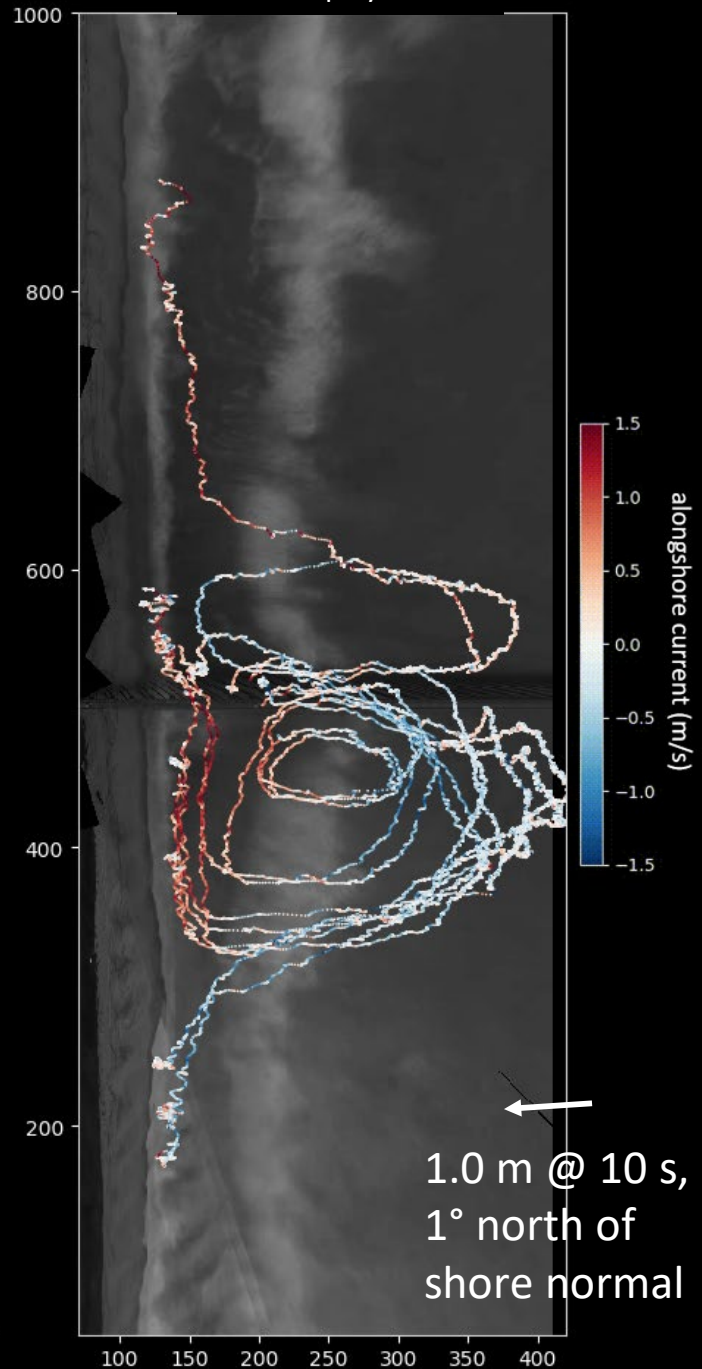




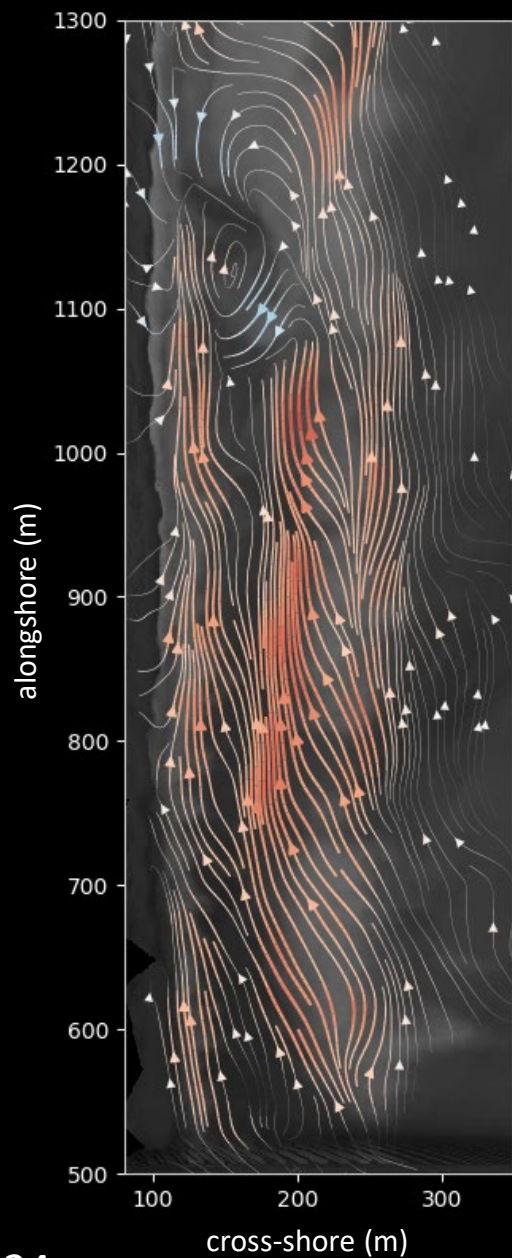
Optical Flow of WAM



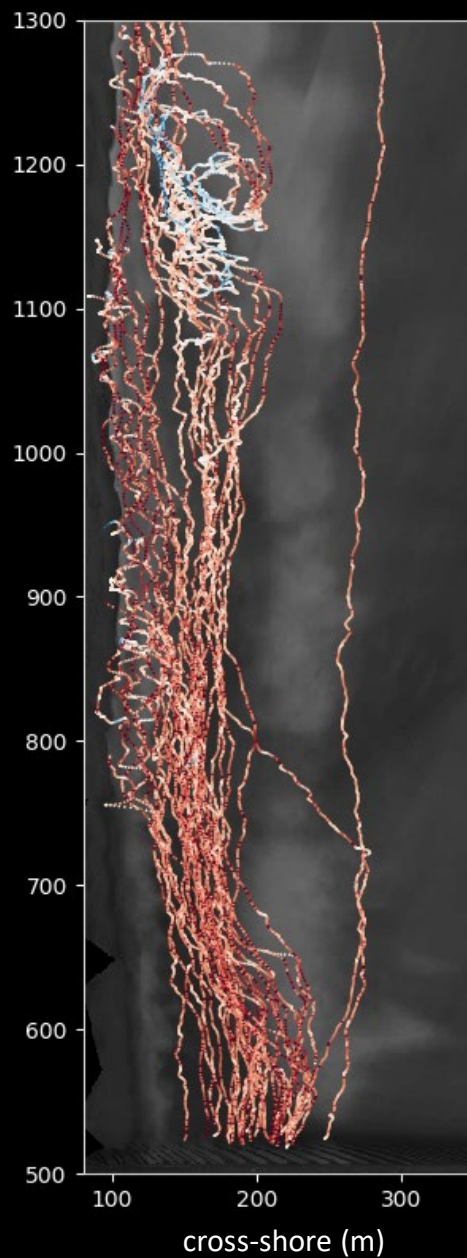
Drifter Deployment



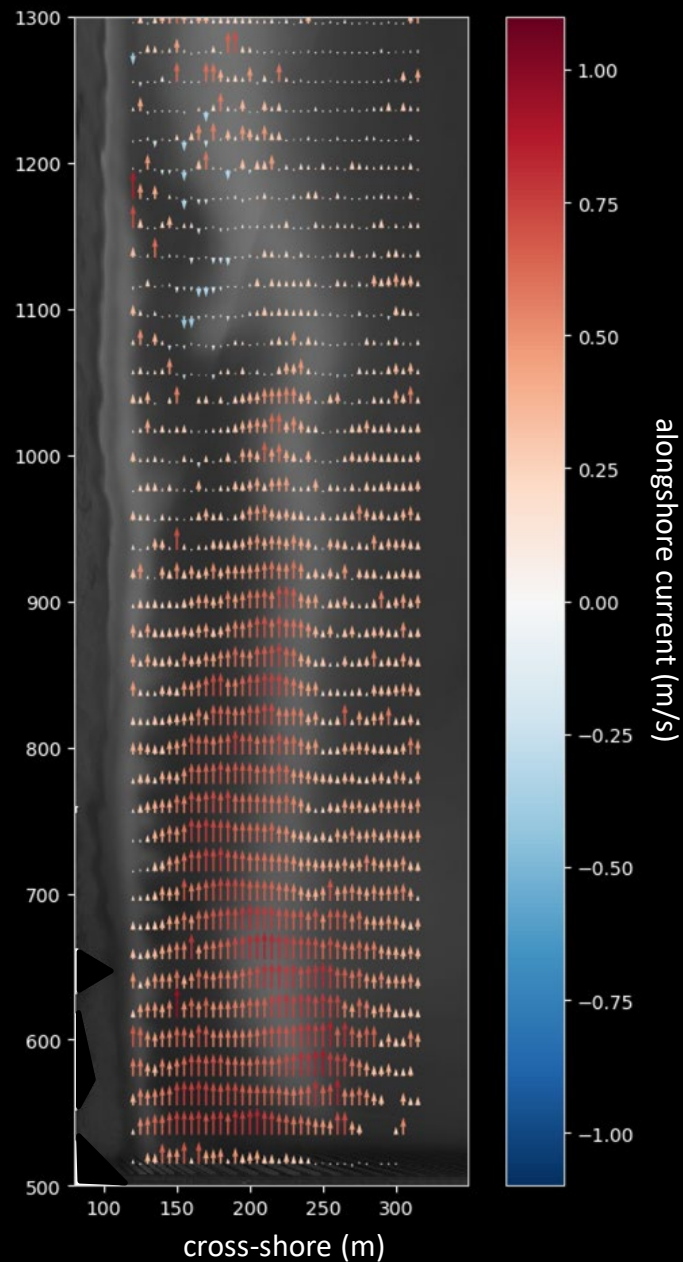
Wave-Averaged Movie



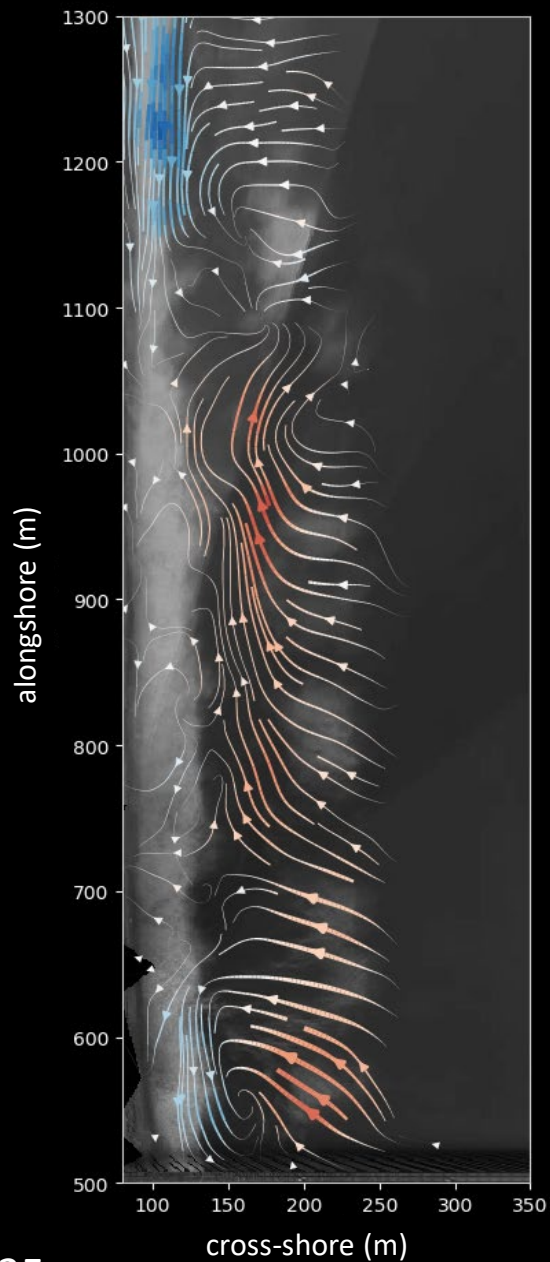
Drifter Deployment



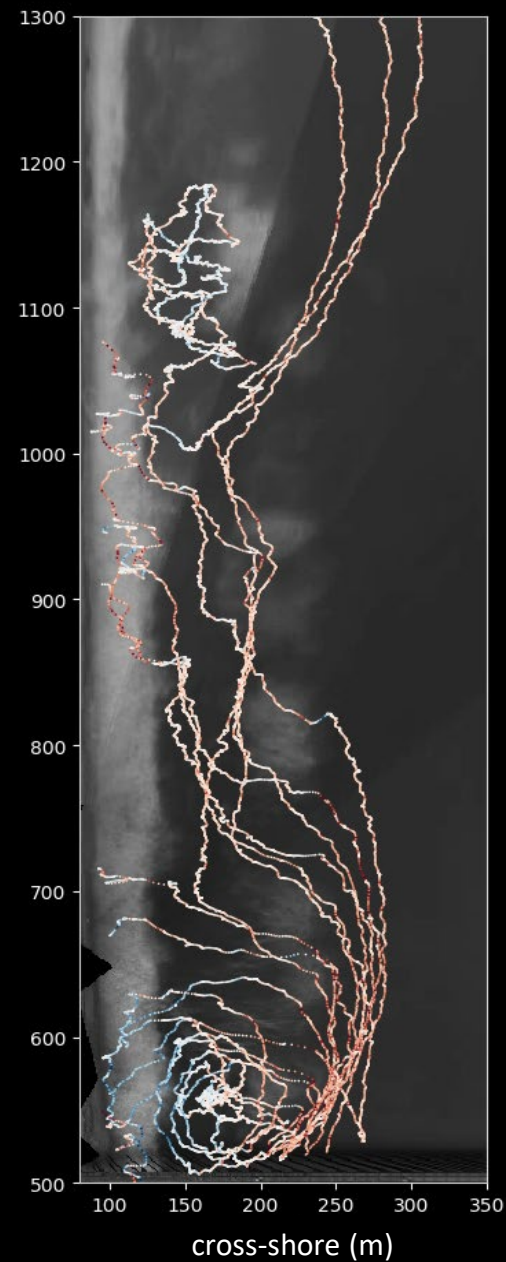
Timestack Method (vBar)



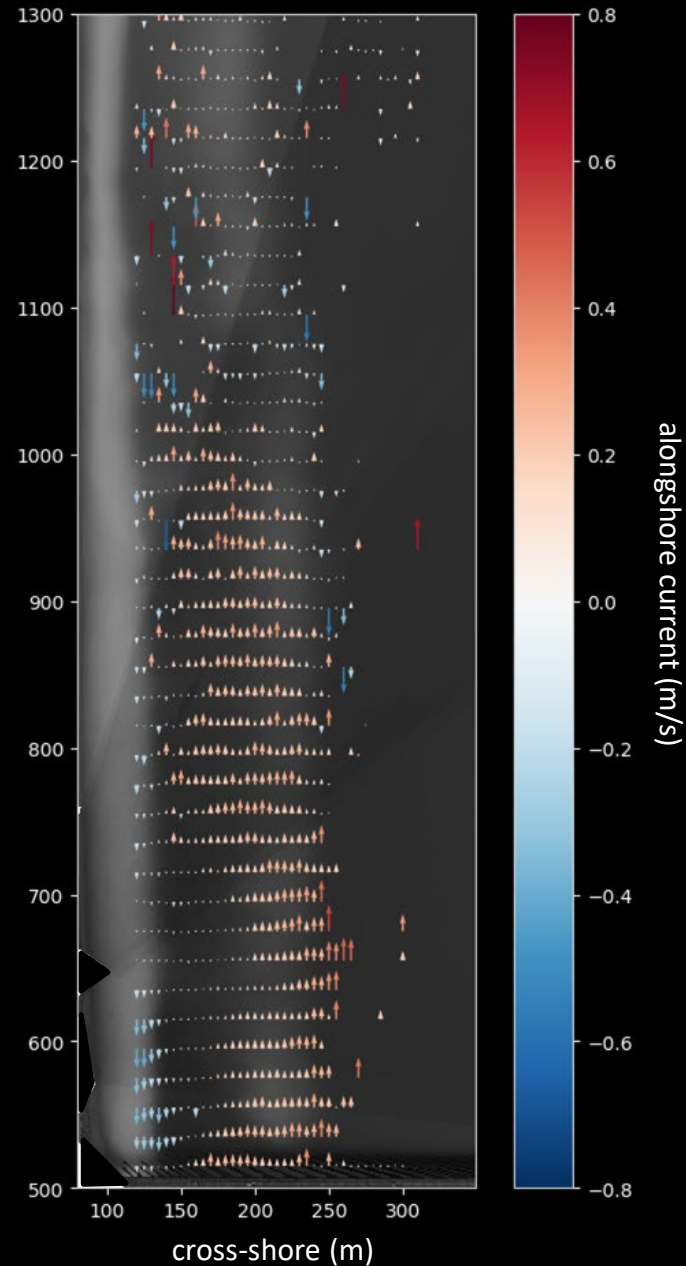
Wave-Averaged Movie



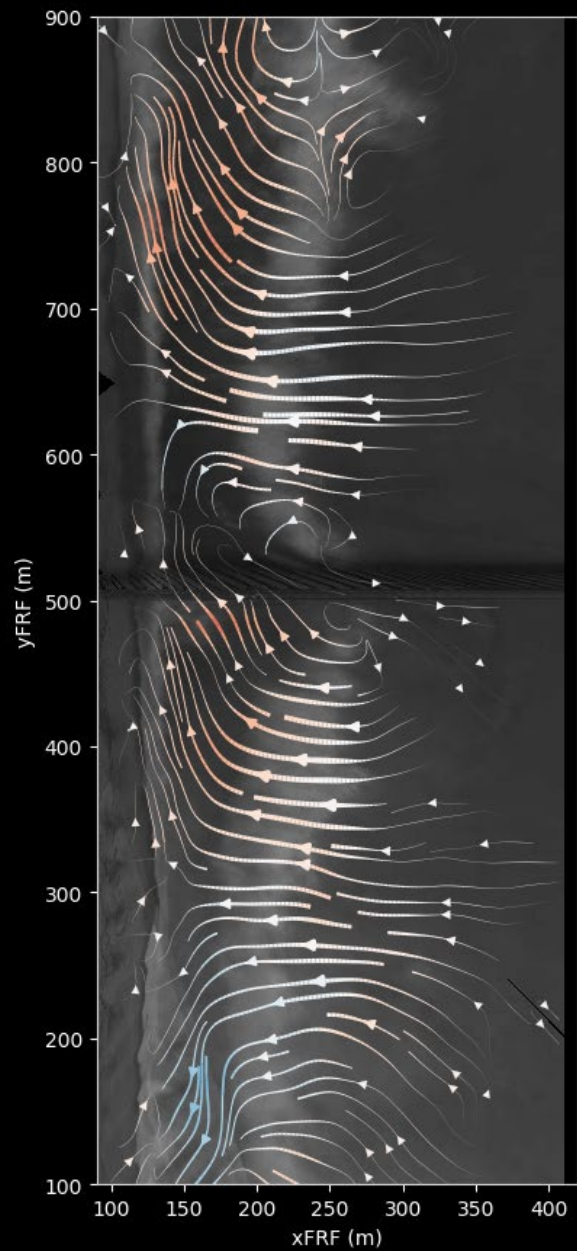
Drifter Deployment



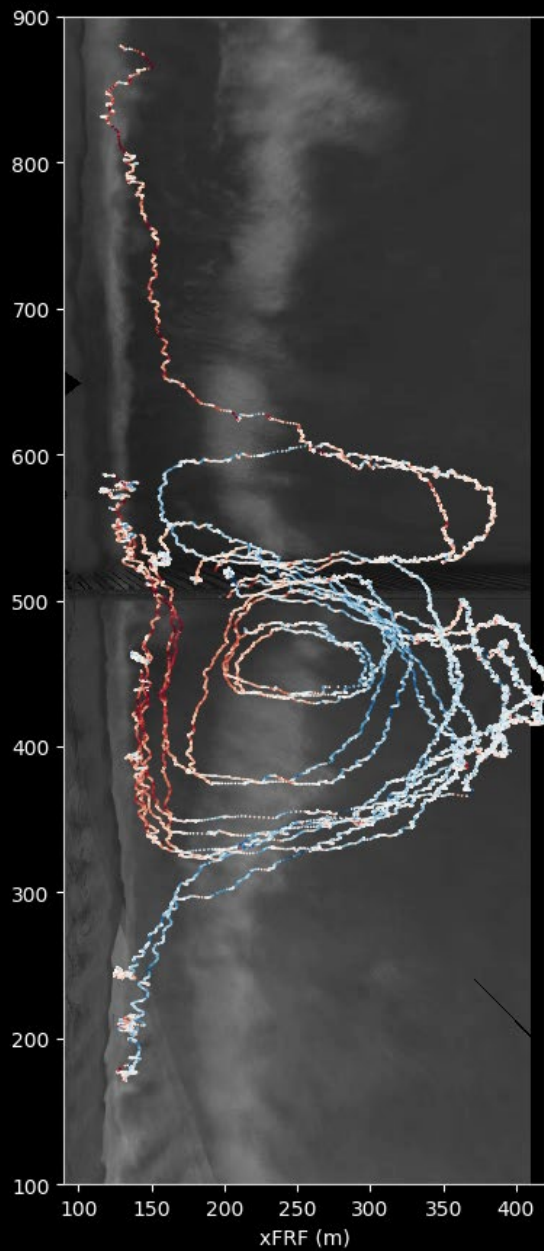
Timestack Method (vBar)



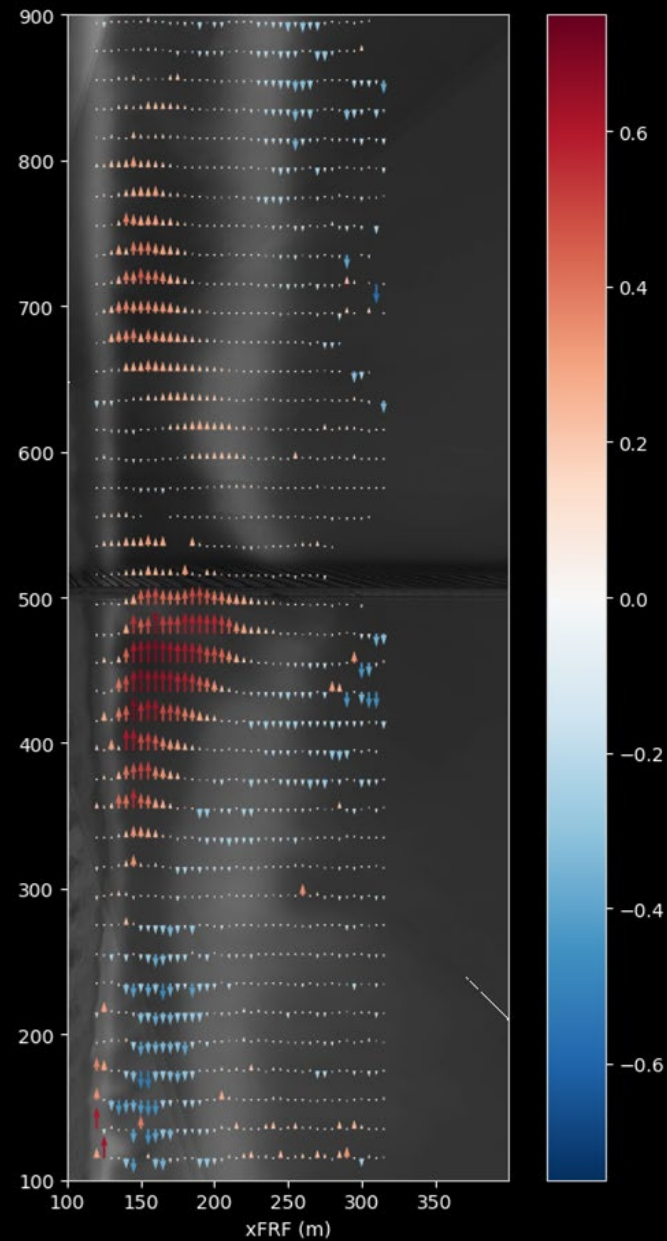
Wave-Averaged Movie



Drifter Deployment

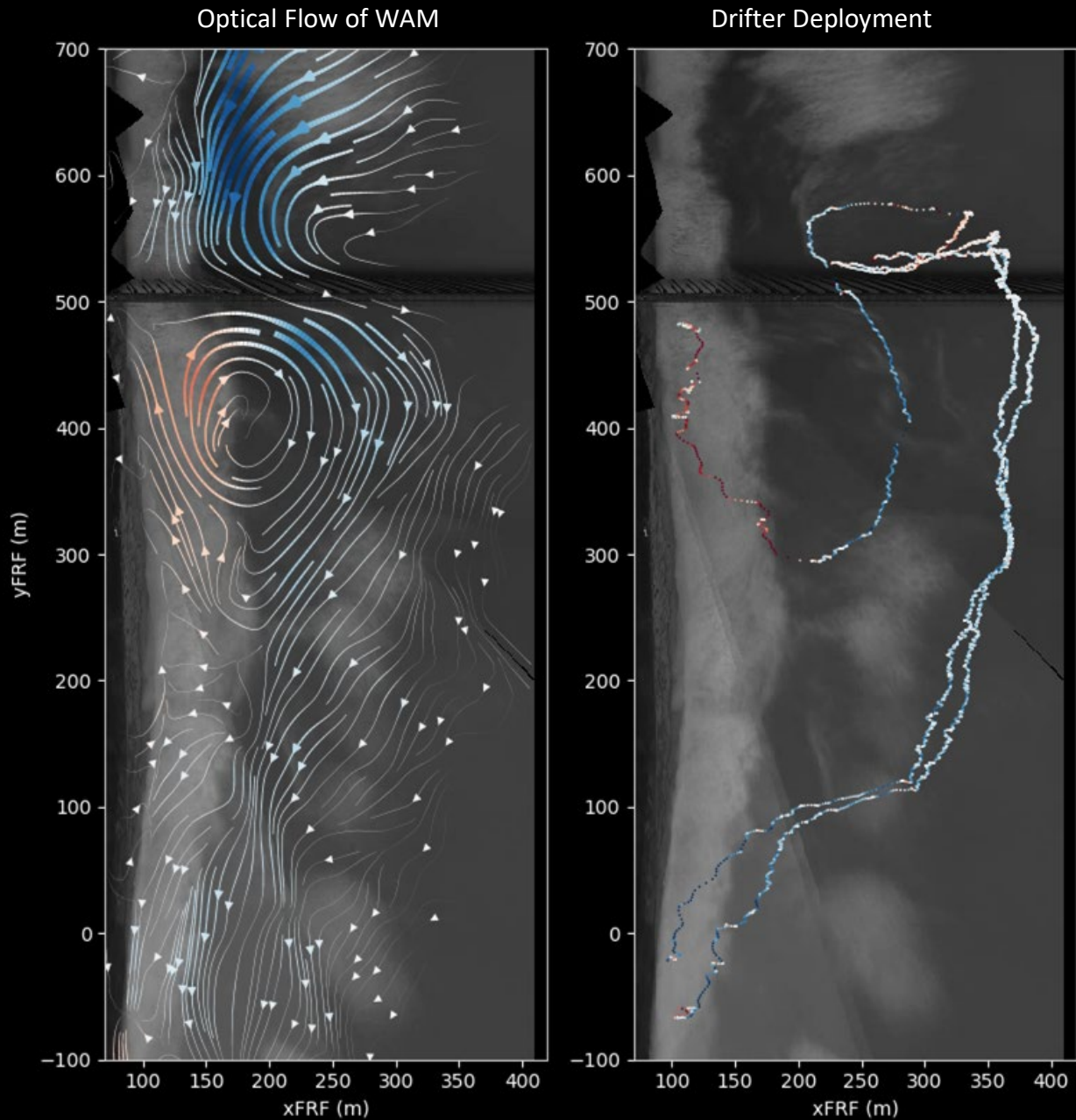


Timestack Method (vBar)

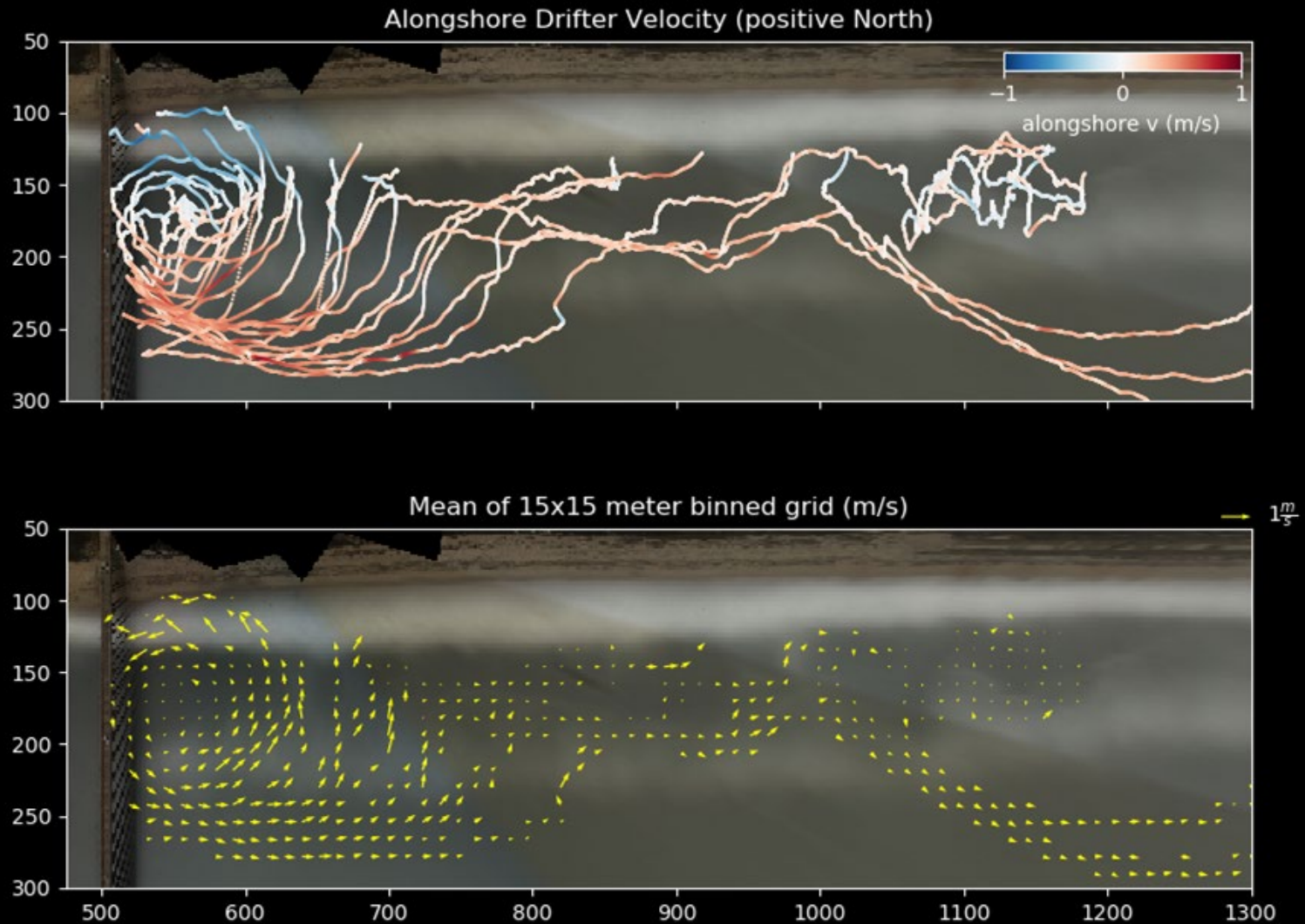


Even a limited number of drifters can provide confidence in the flow pattern derived from the wave-averaged movies.

But ultimately, even the best drifter design is feeling both the mean current and the individual wave components... And its moving through the domain such that 1-to-1 drifter to WAM comparisons are not measuring the same process.

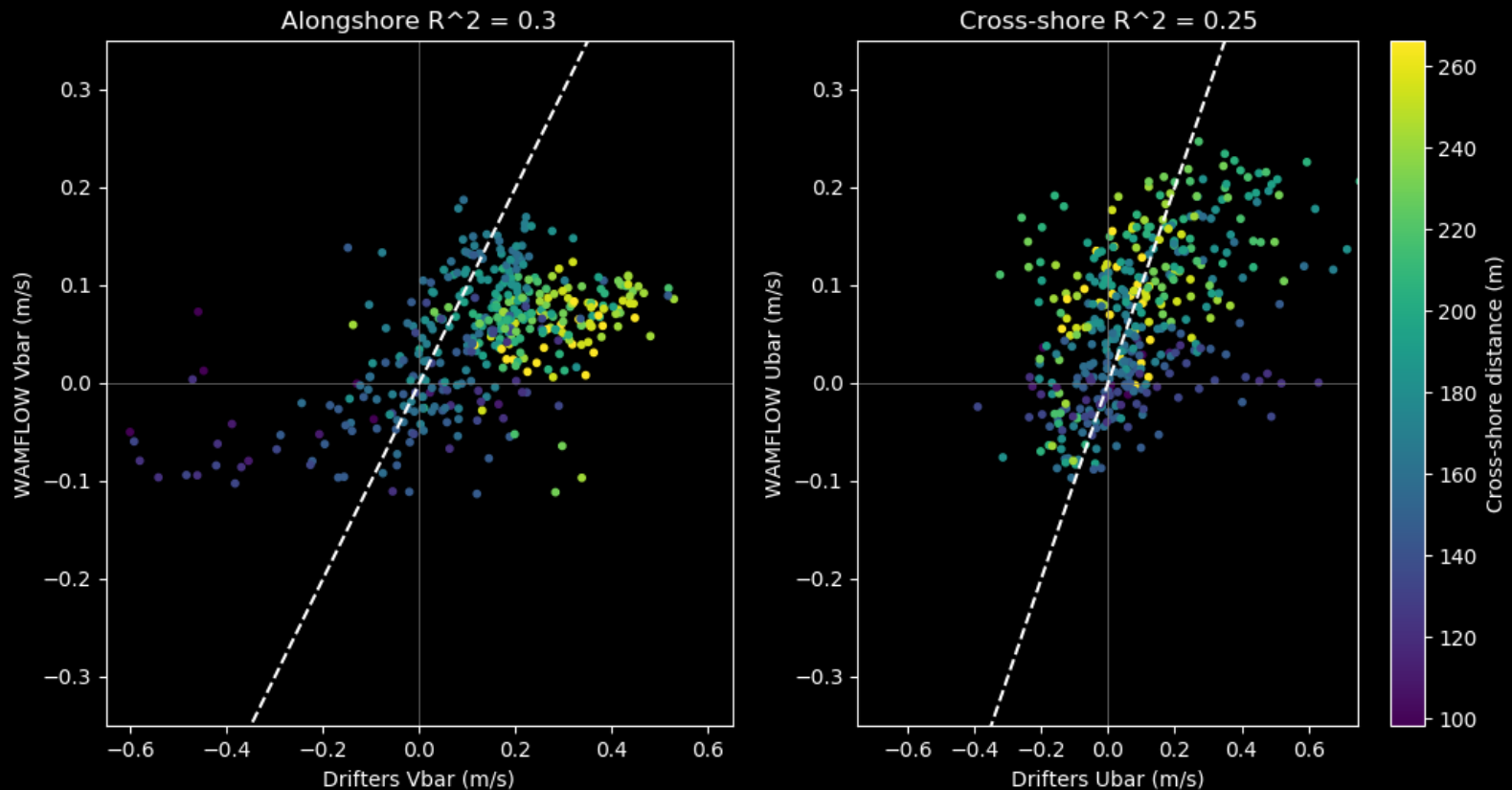


One technique for comparing eulerian and lagrangian measurements: Collapsing lagrangian observations to look at all measurements in an dx,dy spatial bin regardless of time.



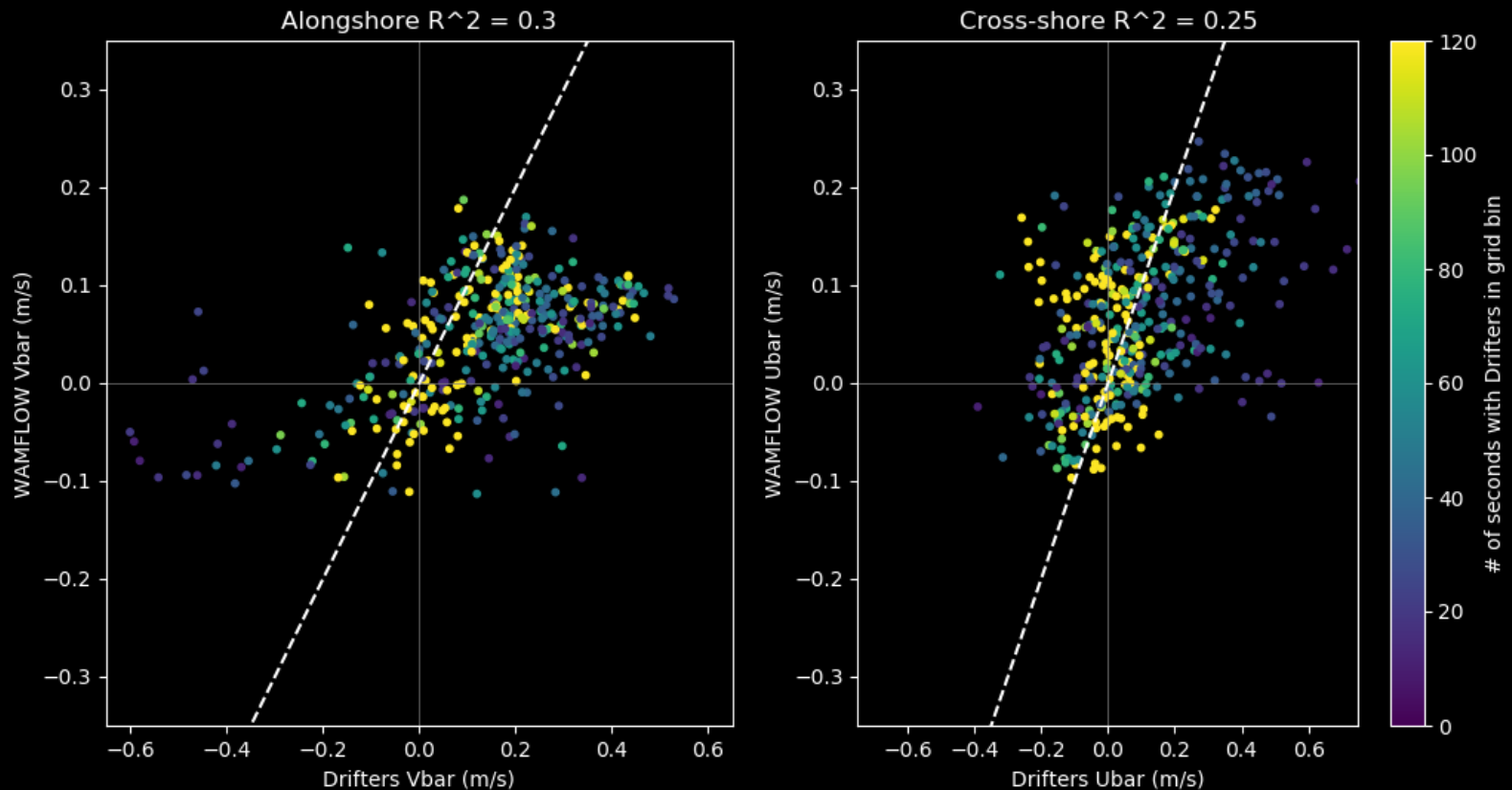
Decent amount of scatter:

- **Underpredict in swash zone**, where depths are shallow, shore-breaking waves dominate and drifters “surf” quickly to shore
- **Underpredict outside of the surf zone**, where foam is intermittent and an “average” current includes zeros due to there being no foam on the surface



Decent amount of scatter:

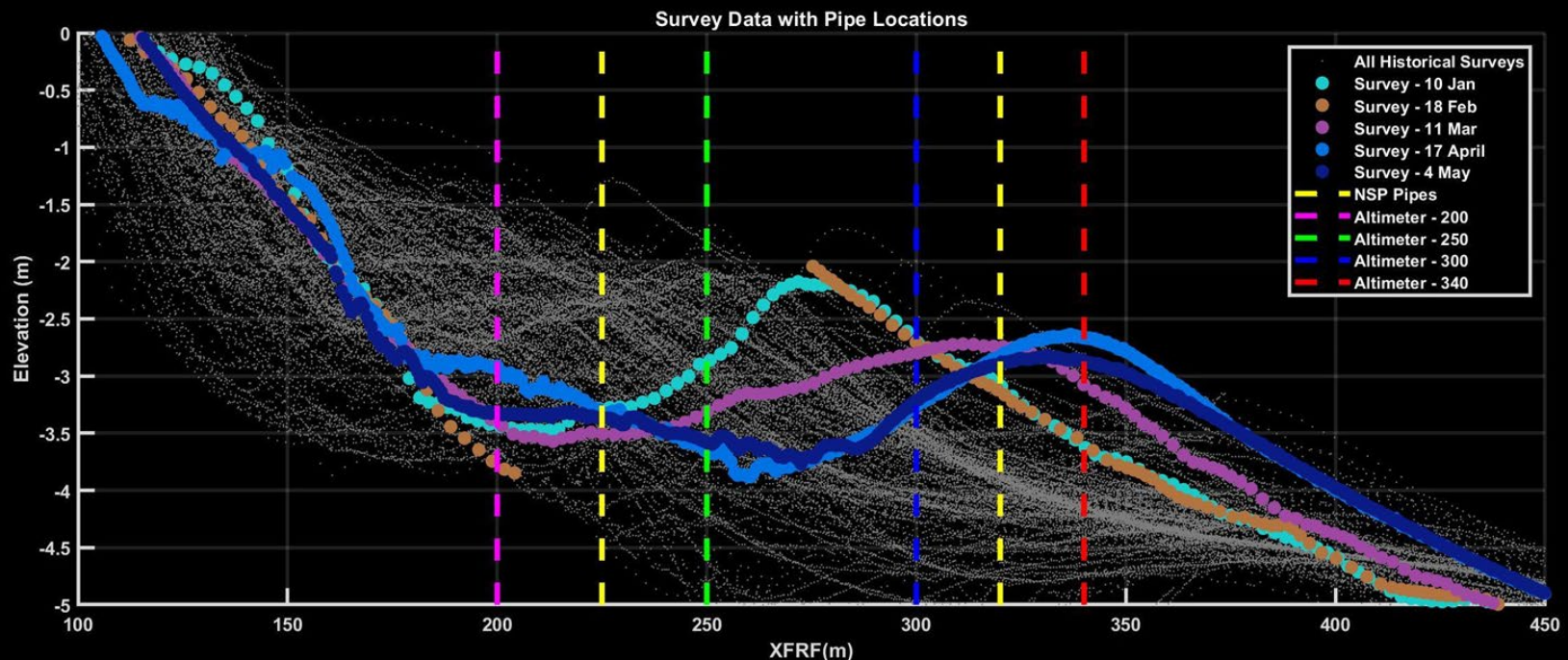
- **Underpredict in swash zone**, where depths are shallow, shore-breaking waves dominate and drifters “surf” quickly to shore
- **Underpredict outside of the surf zone**, where foam is intermittent and an “average” current includes zeros due to there being no foam on the surface
- Ultimately, **the scatter is also a consequence of the number of observations**, fewer observations = more wave-by-wave velocity, more observations = more mean flow



Future Validation & Development

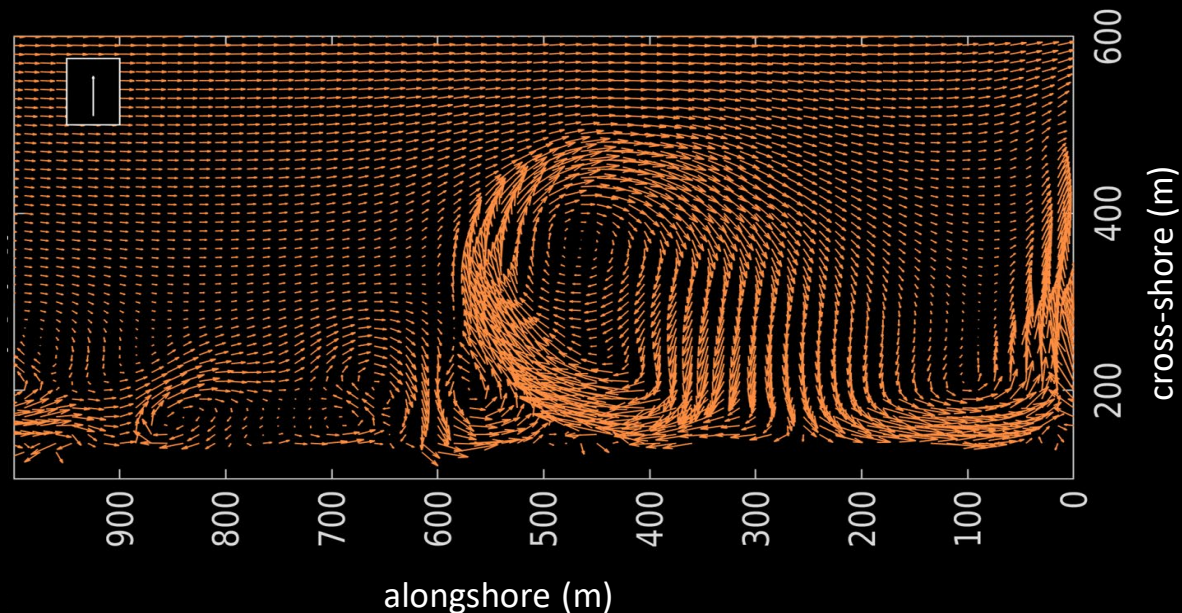
Plan to leverage stationary current profile data collected this spring at the FRF by the Nearshore Processes Research project

- Will provide a range of wave, water level, and wind conditions
- Frequent bathymetric surveys

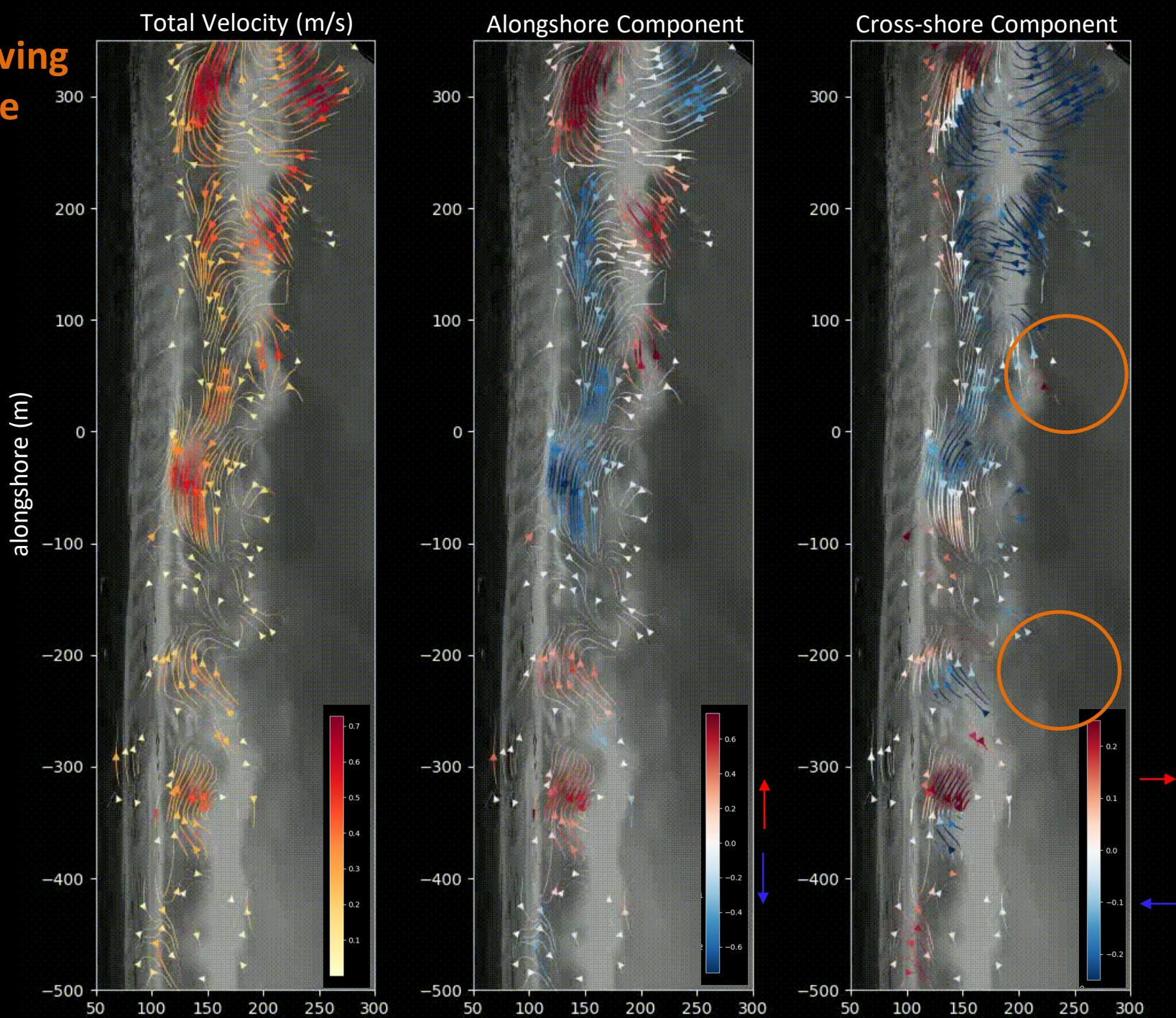


Future Validation & Development

- Plan to deploy drifters again in DUNEX
 - Targeting the circulation patterns from a large wave event
- Data assimilation techniques
- Model/data comparisons
- Standardized Argus product (POH mini-argus pilot)

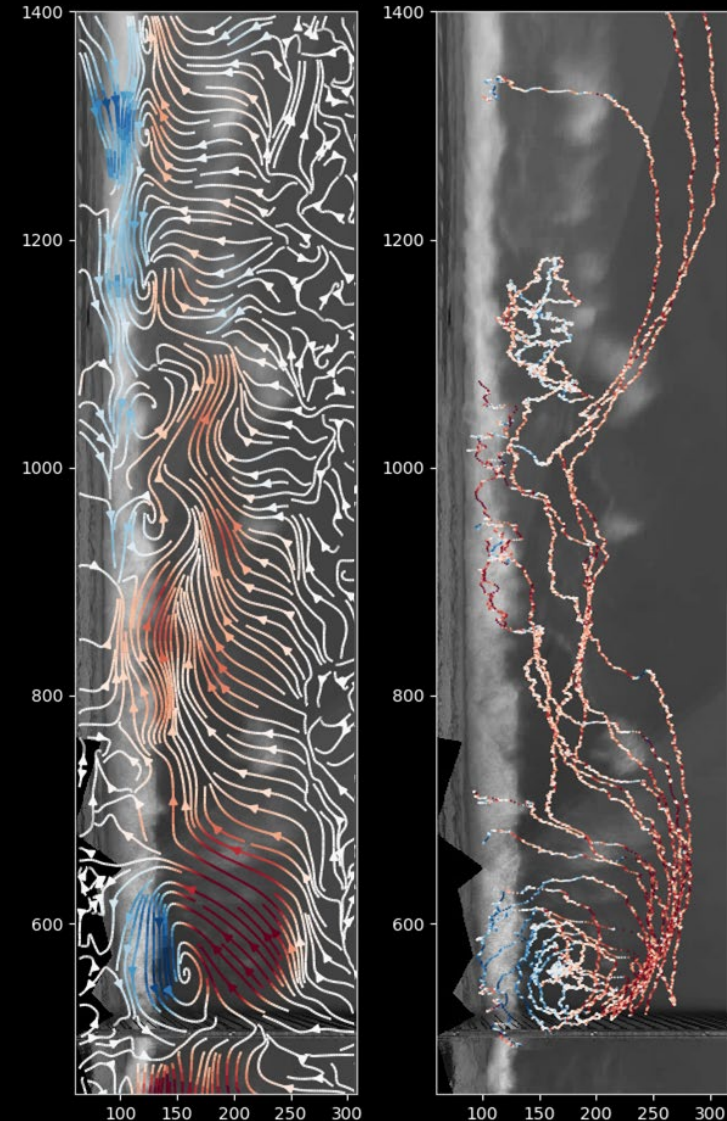


2 min moving
average



New approach, with intriguing potential

- Can use time-averaged imagery to resolve 2-D flow patterns at scales of 10 to 100s of meters within the surf zone
- Initial results qualitatively similar to drifter patterns and quantitatively similar to other optical methods
- Considerable work still to be done... sensitivities to conditions, image quality, averaging windows, optical flow parameters

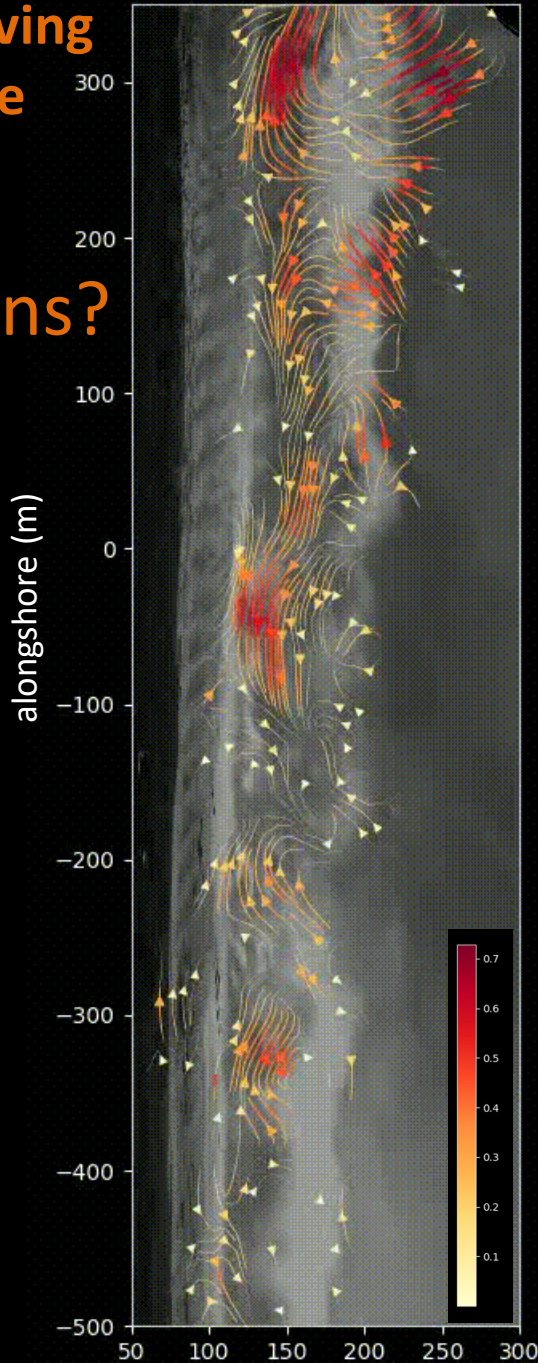


2 min moving
average

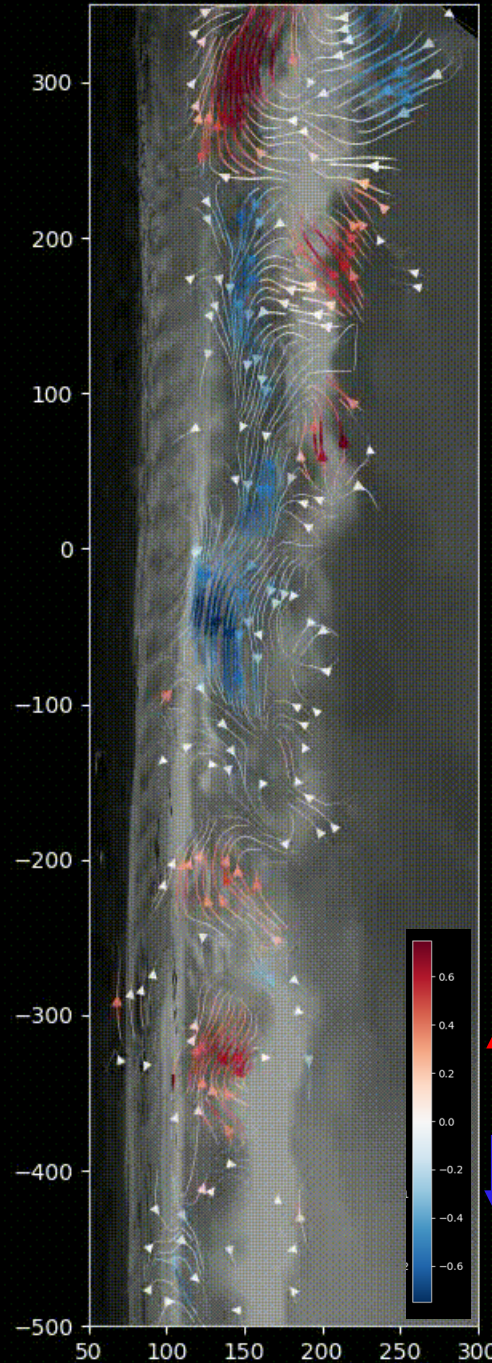
Questions?

Thanks to the
FRF crew!

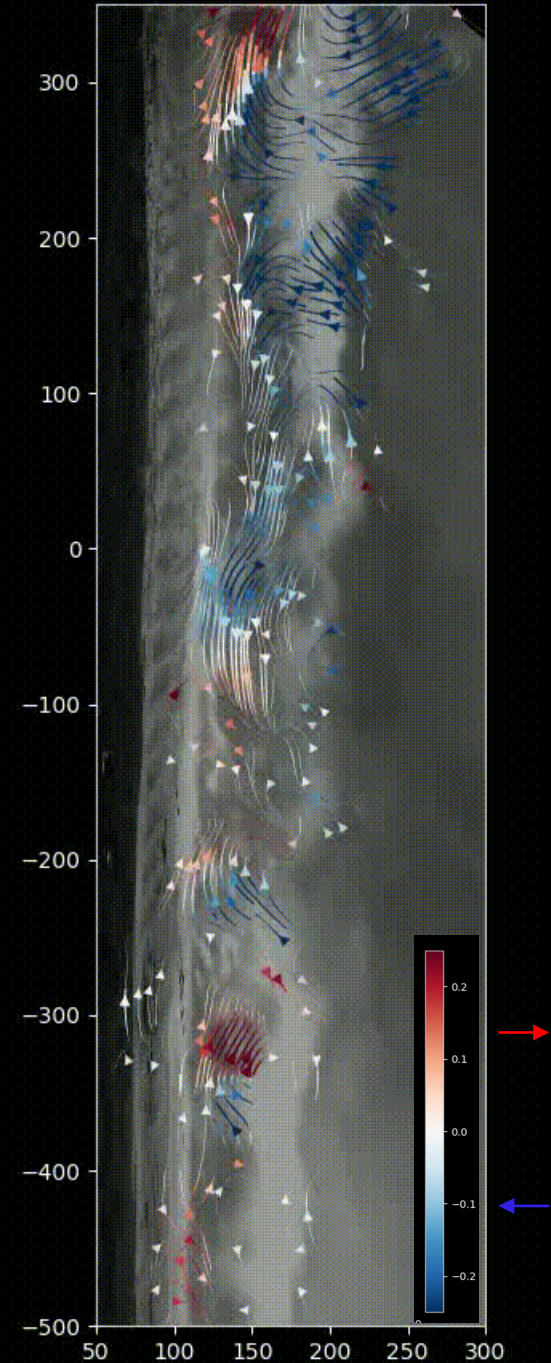
Total Velocity (m/s)



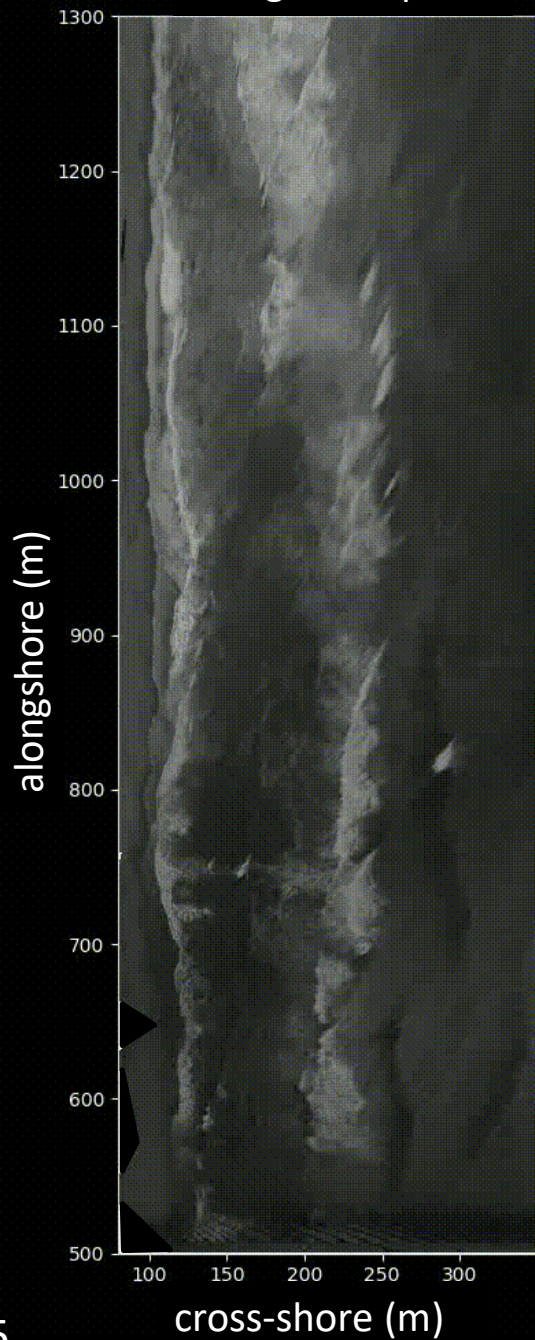
Alongshore Component



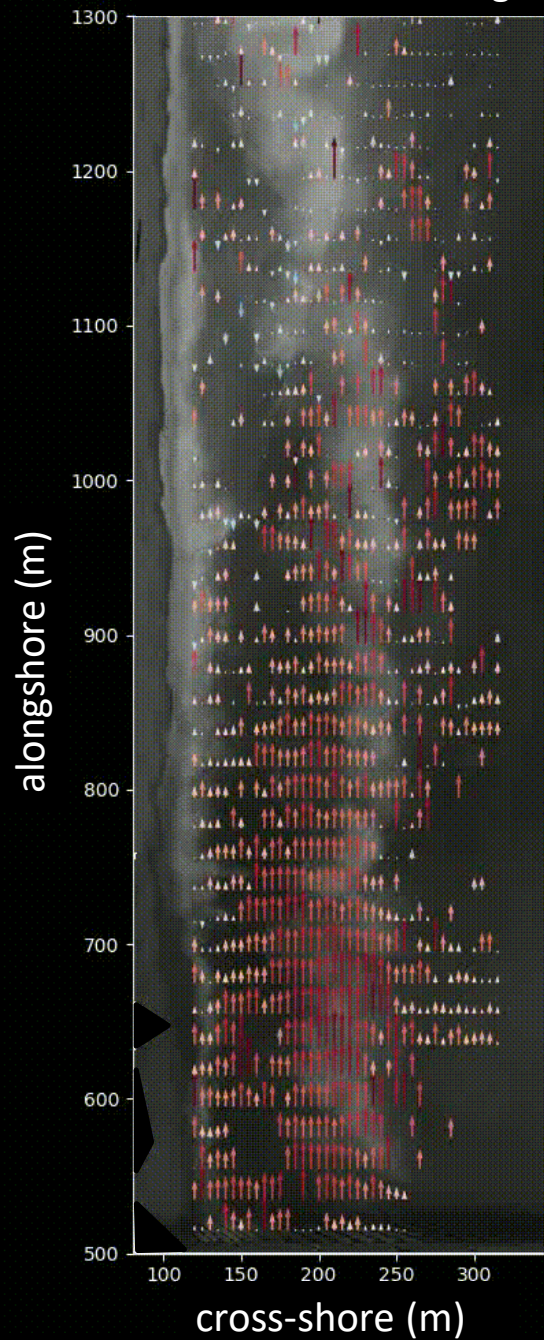
Cross-shore Component



Merged Snaps



2.5 min Time Average



Full 17 min Average

